CSE 549: Genome Assembly De Bruijn Graph

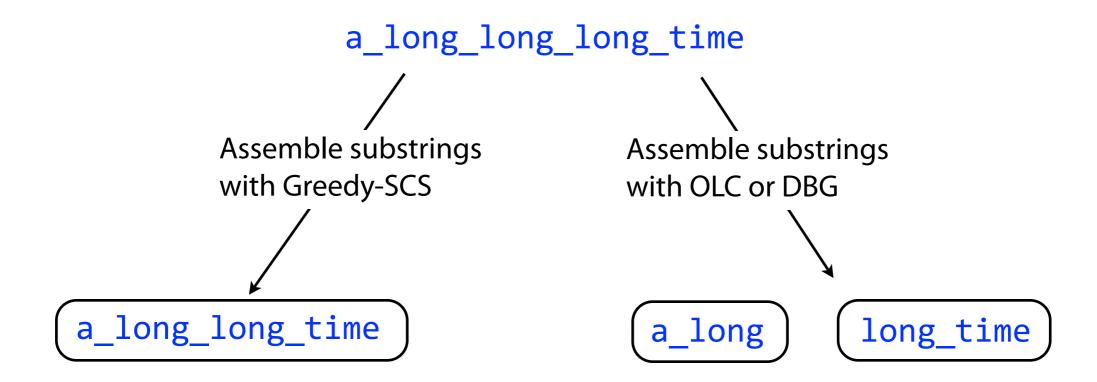


Real-world assembly methods

OLC: Overlap-Layout-Consensus assembly

DBG: De Bruijn graph assembly

Both handle unresolvable repeats by essentially *leaving them out*Unresolvable repeats break the assembly into fragments
Fragments are *contigs* (short for *contiguous*)



De Bruijn graph assembly

A formulation conceptually similar to overlapping/SCS, but has some potentially helpful properties not shared by SCS.

k-mer

"k-mer" is a substring of length k

S: **GGCGATTCATCG** *mer*: from Greek meaning "part"

A 4-mer of *S*:

All 3-mers of *S*: GGC

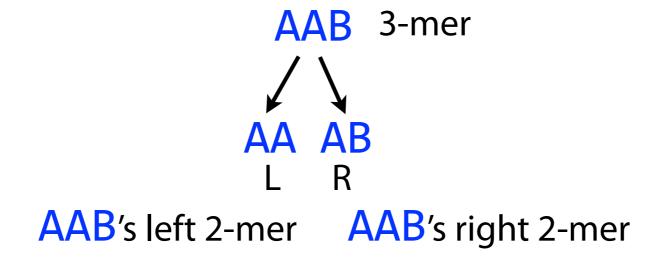
GCG CGA GAT ATT TTC TCA CAT ATC TCG

I'll use "k-1-mer" to refer to a substring of length k - 1

As usual, we start with a collection of reads, which are substrings of the reference genome.

AAA, AAB, ABB, BBB, BBA

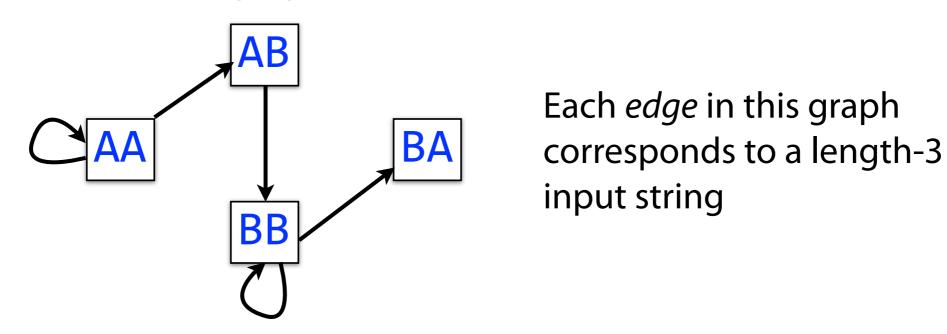
AAB is a k-mer (k = 3). AA is its left k-1-mer, and AB is its right k-1-mer.

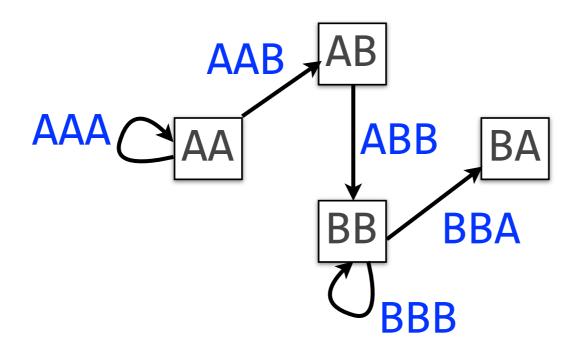


Take each length-3 input string and split it into two overlapping substrings of length 2. Call these the *left* and *right 2-mers*.

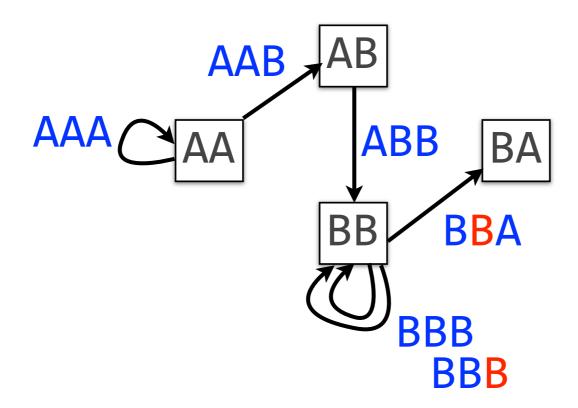
AAABBBA

Let 2-mers be nodes in a new graph. Draw a directed edge from each left 2-mer to corresponding right 2-mer:





An edge corresponds to an overlap (of length k-2) between two k-1 mers. More precisely, it corresponds to a k-mer from the input.



If we add one more B to our input string: AAABBBBA, and rebuild the De Bruijn graph accordingly, we get a *multiedge*.

Directed multigraph

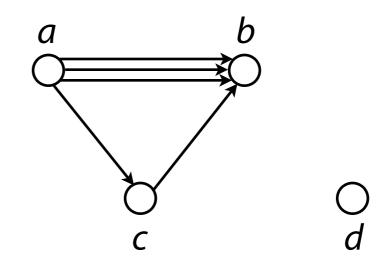
Directed multigraph G(V, E) consists of set of *vertices, V* and multiset of *directed edges, E*

Otherwise, like a directed graph

Node's *indegree* = # incoming edges

Node's *outdegree* = # outgoing edges

De Bruijn graph is a directed multigraph



$$V = \{a, b, c, d\}$$

 $E = \{(a, b), (a, b), (a, b), (a, c), (c, b)\}$
Repeated ———

Eulerian walk definitions and statements

Node is *balanced* if indegree equals outdegree

Node is semi-balanced if indegree differs from outdegree by 1

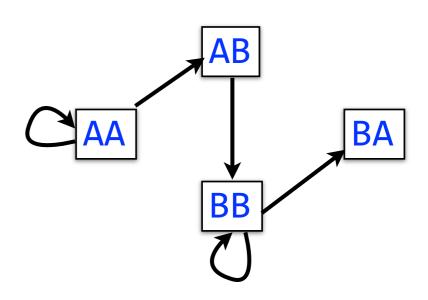
Graph is connected if each node can be reached by some other node

Eulerian walk visits each edge exactly once

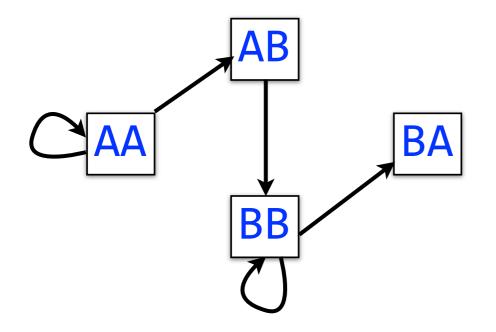
Not all graphs have Eulerian walks. Graphs that do are *Eulerian*. (For simplicity, we won't distinguish Eulerian from semi-Eulerian.)

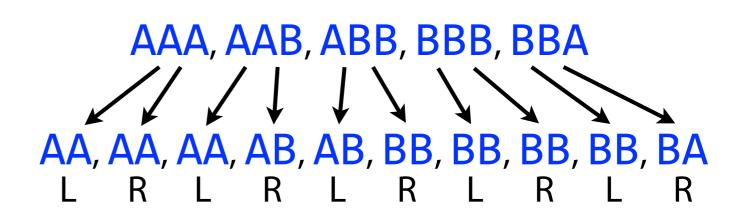
A directed, connected graph is Eulerian if and only if it has at most 2 semi-balanced nodes and all other nodes are balanced

Jones and Pevzner section 8.8



Back to our De Bruijn graph





Is it Eulerian? Yes

Argument 1: $AA \rightarrow AA \rightarrow AB \rightarrow BB \rightarrow BB \rightarrow BA$

Argument 2: AA and BA are semi-balanced, AB and BB are balanced

A procedure for making a De Bruijn graph for a genome

Assume *perfect sequencing* where each length-*k* substring is sequenced exactly once with no errors

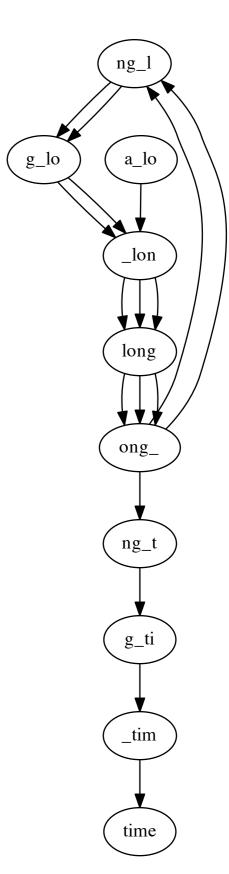
Pick a substring length *k*: 5

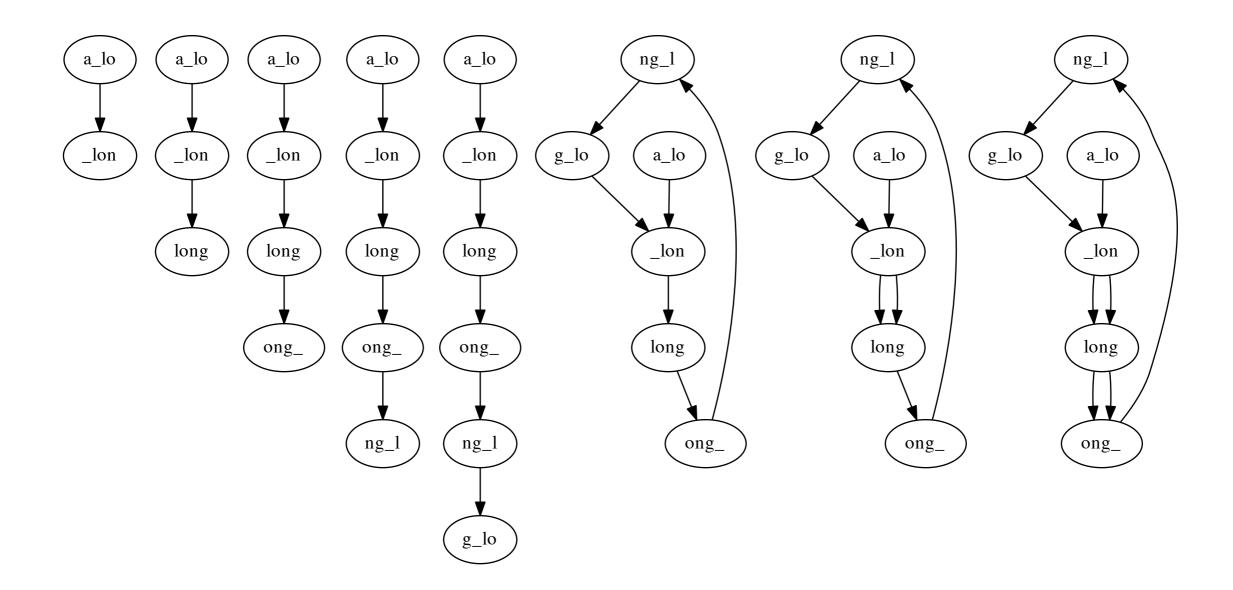
Start with an input string: a_long_long_time

Take each *k* mer and split into left and right *k*-1 mers

long_ long ong_

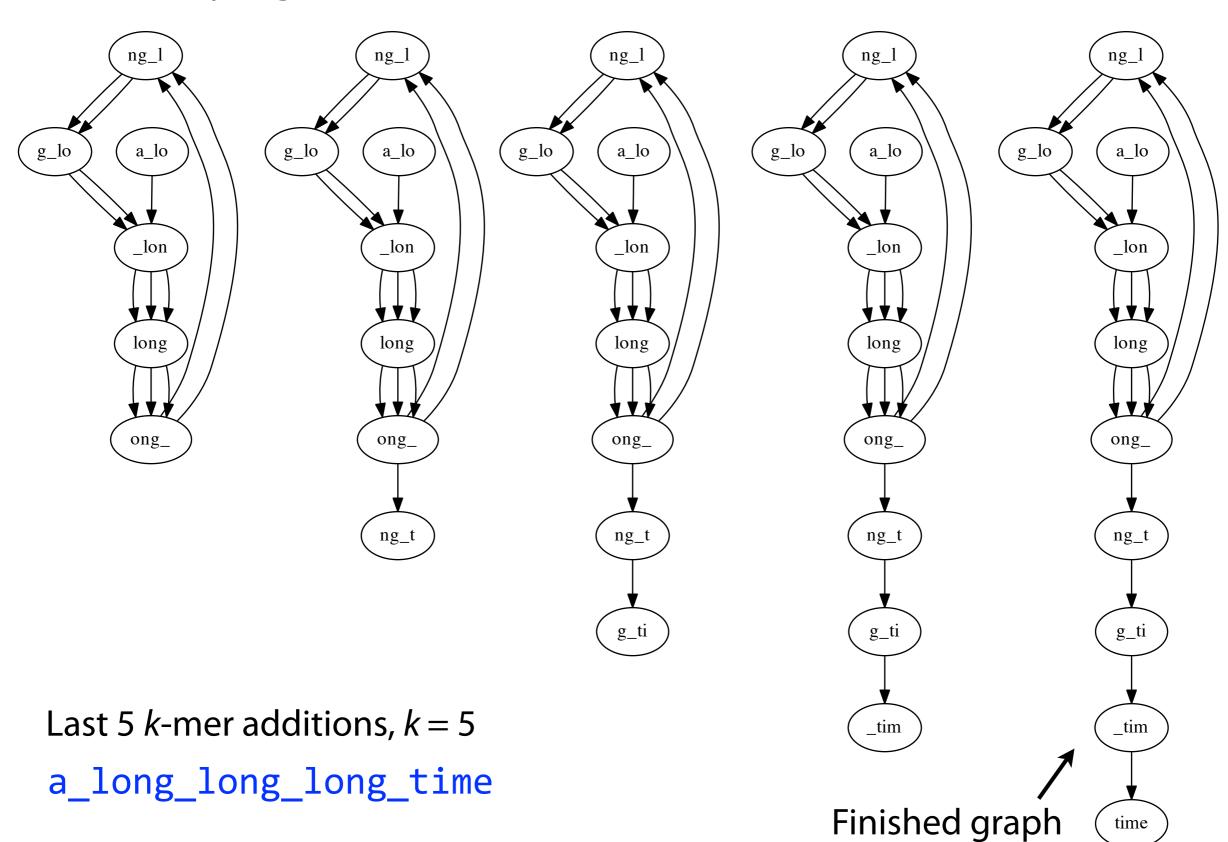
Add k-1 mers as nodes to De Bruijn graph (if not already there), add edge from left k-1 mer to right k-1 mer





First 8 k-mer additions, k = 5

a_long_long_time



With perfect sequencing, this procedure always yields an Eulerian graph. Why?

Node for *k*-1-mer from left end is semi-balanced with one more outgoing edge than incoming *

Node for *k*-1-mer at right end is semi-balanced with one more incoming than outgoing *

Other nodes are balanced since # times k-1-mer occurs as a left k-1-mer = # times it occurs as a right k-1-mer

ng_l _lon long ong_ ng_t g_ti _tim

^{*} Unless genome is circular

De Bruijn graph implementation

```
class DeBruijnGraph:
   """ A De Bruijn multigraph built from a collection of strings.
       User supplies strings and k-mer length k. Nodes of the De
       Bruijn graph are k-1-mers and edges join a left k-1-mer to a
       right k-1-mer. """
   @staticmethod
   def chop(st, k):
       """ Chop a string up into k mers of given length
       for i in xrange(0, len(st)-(k-1)): yield st[i:i+k]
    class Node:
       """ Node in a De Bruijn graph, representing a k-1 mer """
       def init (self, km1mer):
            self.km1mer = km1mer
       def hash (self):
            return hash(self.km1mer)
   def __init__(self, strIter, k):
       """ Build De Bruijn multigraph given strings and k-mer length k """
        self.G = {} # multimap from nodes to neighbors
       self.nodes = {} # maps k-1-mers to Node objects
       self.k = k
       for st in strIter:
            for kmer in self.chop(st, k):
                km1L, km1R = kmer[:-1], kmer[1:]
                nodeL, nodeR = None, None
                if km1L in self.nodes:
                    nodeL = self.nodes[km1L]
                else:
                    nodeL = self.nodes[km1L] = self.Node(km1L)
                if km1R in self.nodes:
                    nodeR = self.nodes[km1R]
                else:
                    nodeR = self.nodes[km1R] = self.Node(km1R)
               self.G.setdefault(nodeL, []).append(nodeR)
```

Chop string into k-mers

For each *k*-mer, find left and right *k*-1-mers

Create corresponding nodes (if necessary) and add edge

For Eulerian graph, Eulerian walk can be found in O(|E|) time. |E| is # edges.

Convert graph into one with Eulerian *cycle* (add an edge to make all nodes balanced), then use this recursive procedure

Insight: If C is a cycle in an Eulerian graph, then after removing edges of C, remaining connected components are also Eulerian

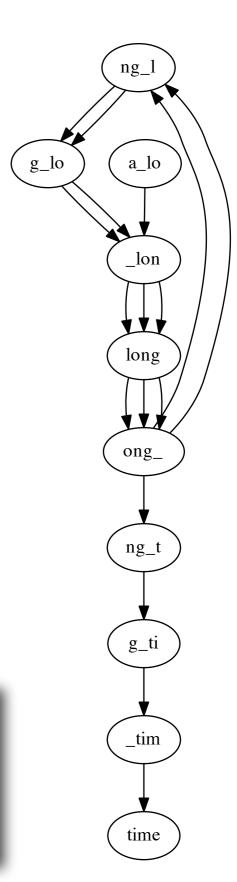
```
# Make all nodes balanced, if not already
tour = []
# Pick arbitrary node
src = g.iterkeys().next()
def __visit(n):
   while len(g[n]) > 0:
      dst = g[n].pop()
      visit(dst)
   tour.append(n)
__visit(src)
# Reverse order, omit repeated node
tour = tour[::-1][:-1]
# Turn tour into walk, if necessary
```

Full illustrative De Bruijn graph and Eulerian walk:

http://nbviewer.ipython.org/7237207

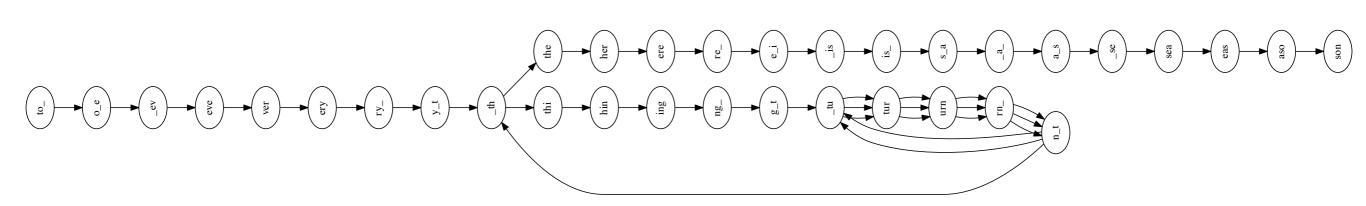
Example where Eulerian walk gives correct answer for small *k* whereas Greedy-SCS could spuriously collapse repeat:

```
>>> G = DeBruijnGraph(["a_long_long_long_time"], 5)
>>> print G.eulerianWalkOrCycle()
['a_lo', '_lon', 'long', 'ong_', 'ng_l', 'g_lo',
'_lon', 'long', 'ong_', 'ng_l', 'g_lo', '_lon',
'long', 'ong_', 'ng_t', 'g_ti', '_tim', 'time']
```



Another example Eulerian walk:

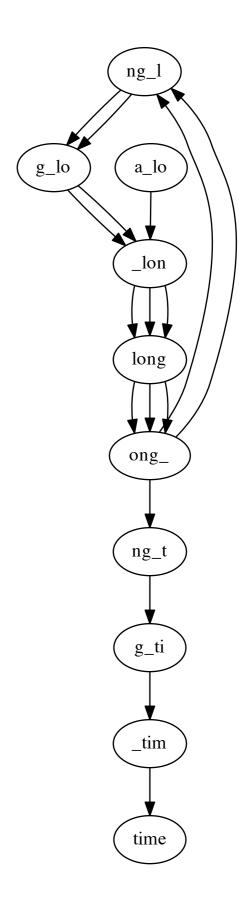
```
>>> st = "to_every_thing_turn_turn_turn_there_is_a_season"
>>> G = DeBruijnGraph([st], 4)
>>> path = G.eulerianWalkOrCycle()
>>> superstring = path[0] + ''.join(map(lambda x: x[-1], path[1:]))
>>> print superstring
to_every_thing_turn_turn_there_is_a_season
```



Recall: This is not generally possible or tractable in the overlap/SCS formulation

Assuming perfect sequencing, procedure yields graph with Eulerian walk that can be found efficiently.

We saw cases where Eulerian walk corresponds to the original superstring. Is this always the case?



No: graph can have multiple Eulerian walks, only one of which corresponds to original superstring

Right: graph for ZABCDABEFABY, k = 3

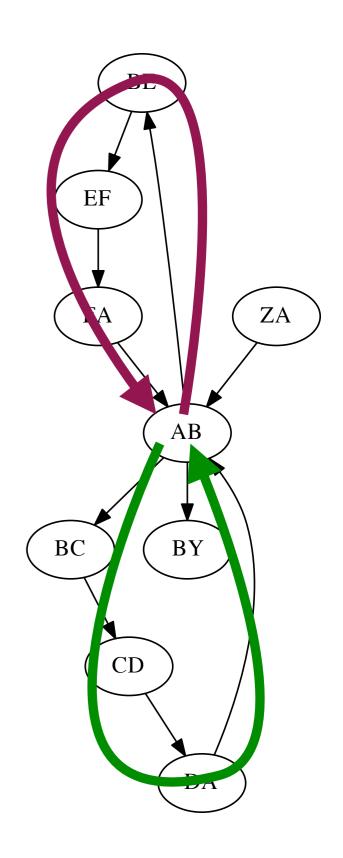
Alternative Eulerian walks:

$$ZA \rightarrow AB \rightarrow BE \rightarrow EF \rightarrow FA \rightarrow AB \rightarrow BC \rightarrow CD \rightarrow DA \rightarrow AB \rightarrow BY$$

$$ZA \rightarrow AB \rightarrow BC \rightarrow CD \rightarrow DA \rightarrow AB \rightarrow BE \rightarrow EF \rightarrow FA \rightarrow AB \rightarrow BY$$

These correspond to two edge-disjoint directed cycles joined by node AB

AB is a repeat: ZABCDABEFABY



Case where k = 4 works:

```
>>> st = "to_every_thing_turn_turn_turn_there_is_a_season"
>>> G = DeBruijnGraph([st], 4)
>>> path = G.eulerianWalkOrCycle()
>>> superstring = path[0] + ''.join(map(lambda x: x[-1], path[1:]))
>>> print superstring
to_every_thing_turn_turn_there_is_a_season
```

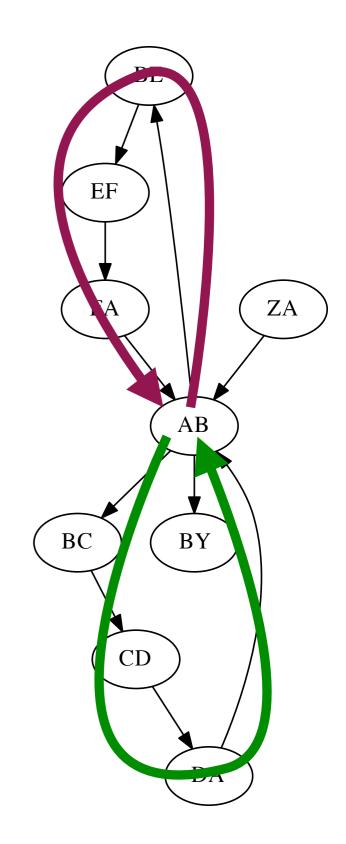
But k = 3 does not:

```
>>> st = "to_every_thing_turn_turn_turn_there_is_a_season"
>>> G = DeBruijnGraph([st], 3)
>>> path = G.eulerianWalkOrCycle()
>>> superstring = path[0] + ''.join(map(lambda x: x[-1], path[1:]))
>>> print superstring
to_every_turn_turn_thing_turn_there_is_a_season
```

Due to repeats that are unresolvable at k = 3

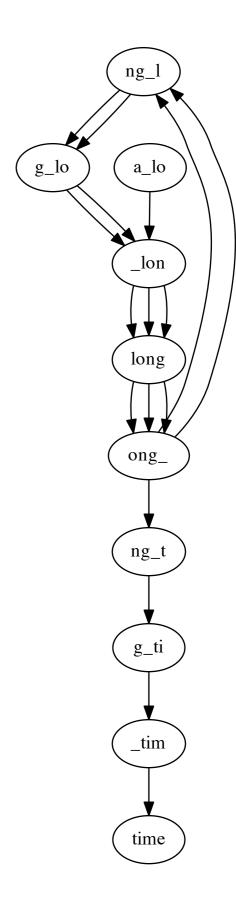
This is the first sign that Eulerian walks can't solve all our problems

Other signs emerge when we think about how actual sequencing differs from our idealized construction



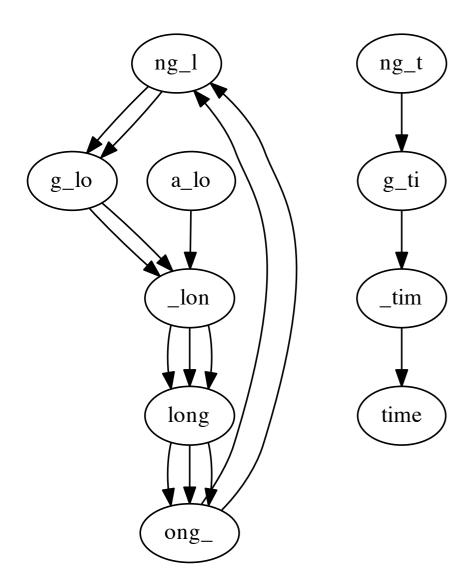
Gaps in coverage can lead to disconnected graph

Graph for a long long long time, k = 5:



Gaps in coverage can lead to disconnected graph

Graph for a long long long time, k = 5 but omitting ong t:

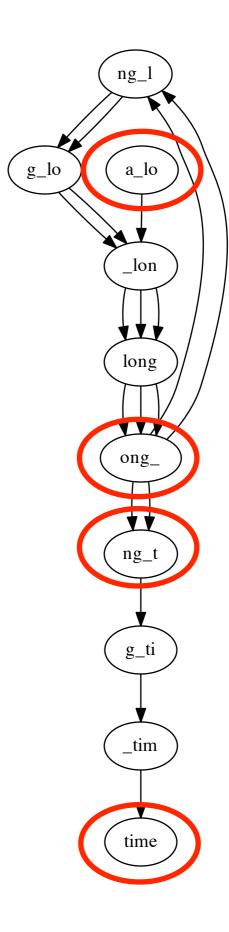


Connected components are individually Eulerian, overall graph is not

Differences in coverage also lead to non-Eulerian graph

Graph for a_long_long_long_time, k = 5 but with *extra copy* of ong_t:

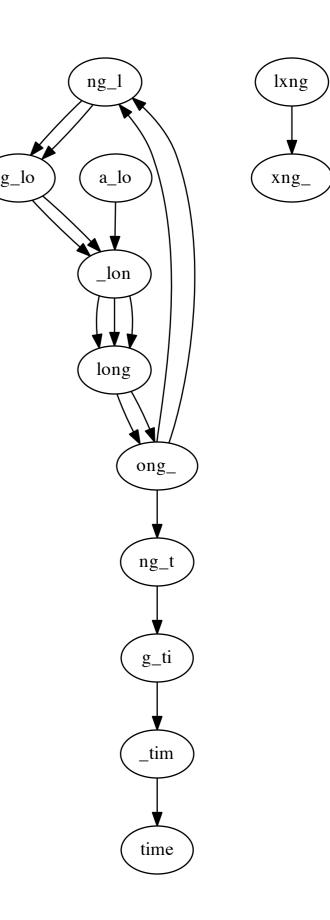
Graph has 4 semi-balanced nodes, isn't Eulerian



Errors and differences between chromosomes also lead to non-Eulerian graphs

Graph for a_long_long_long_time, k = 5 but with error that turns a copy of long_ into lxng_

Graph is not connected; largest component is not Eulerian



Casting assembly as Eulerian walk is appealing, but not practical

Uneven coverage, sequencing errors, etc make graph non-Eulerian

Even if graph were Eulerian, repeats yield many possible walks

Kingsford, Carl, Michael C. Schatz, and Mihai Pop. "Assembly complexity of prokaryotic genomes using short reads." *BMC bioinformatics* 11.1 (2010): 21.

De Bruijn Superwalk Problem (DBSP) is an improved formulation where we seek a walk over the De Bruijn graph, where walk contains each read as a subwalk

Proven NP-hard!

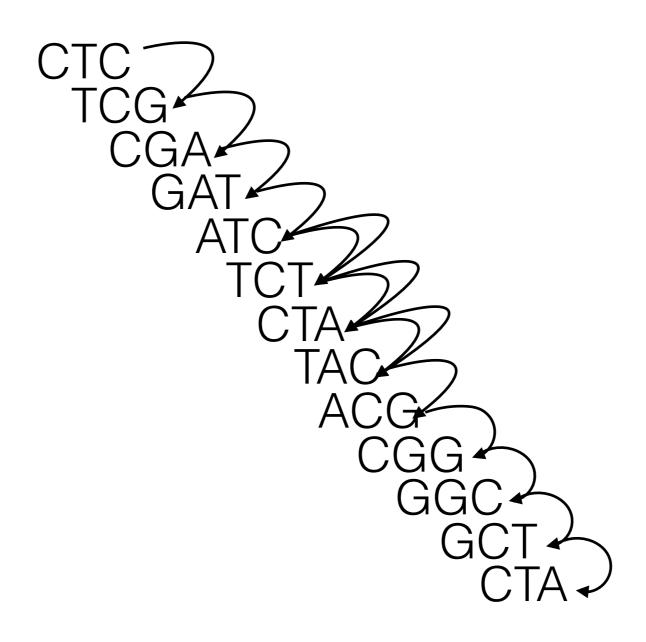
Medvedev, Paul, et al. "Computability of models for sequence assembly." *Algorithms in Bioinformatics*. Springer Berlin Heidelberg, 2007. 289-301.

Uneven coverage foils Eulerian Paths

r1: CTCGATCTAC

r2: ATCTACGGCTA

k=4

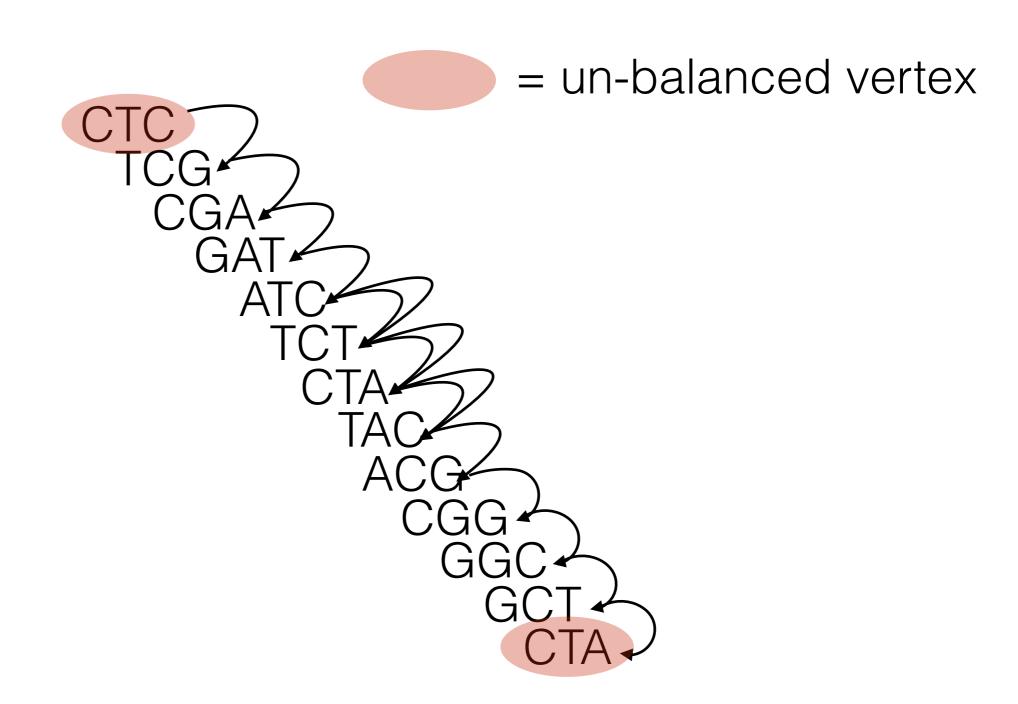


Uneven coverage foils Eulerian Paths

r1: CTCGATCTAC

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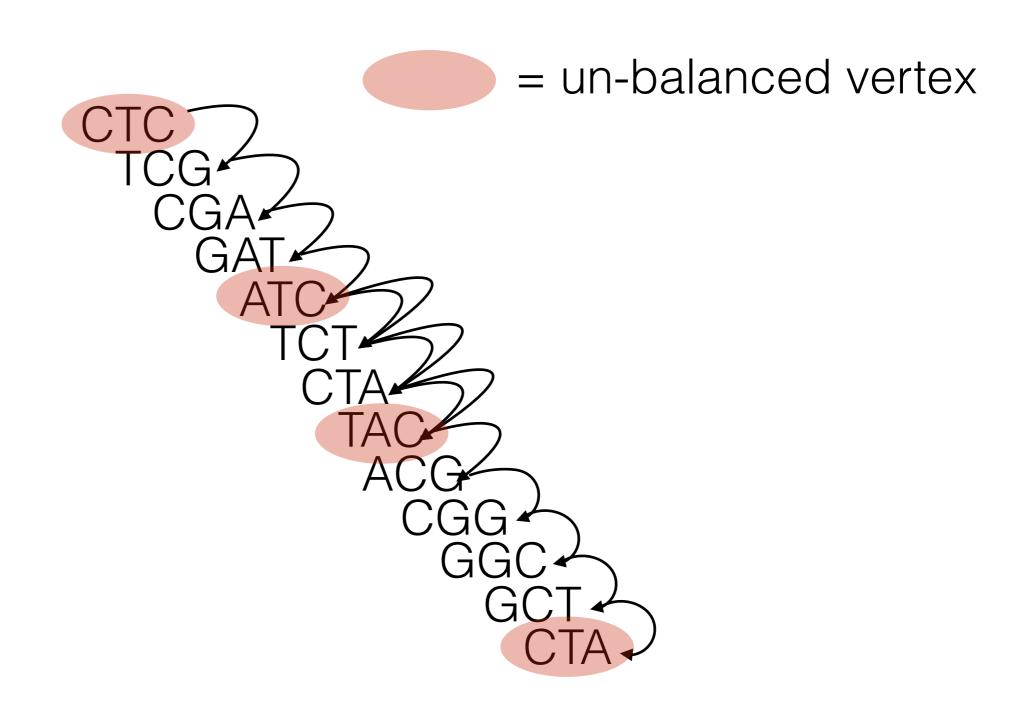


Uneven coverage foils Eulerian Paths

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k=4



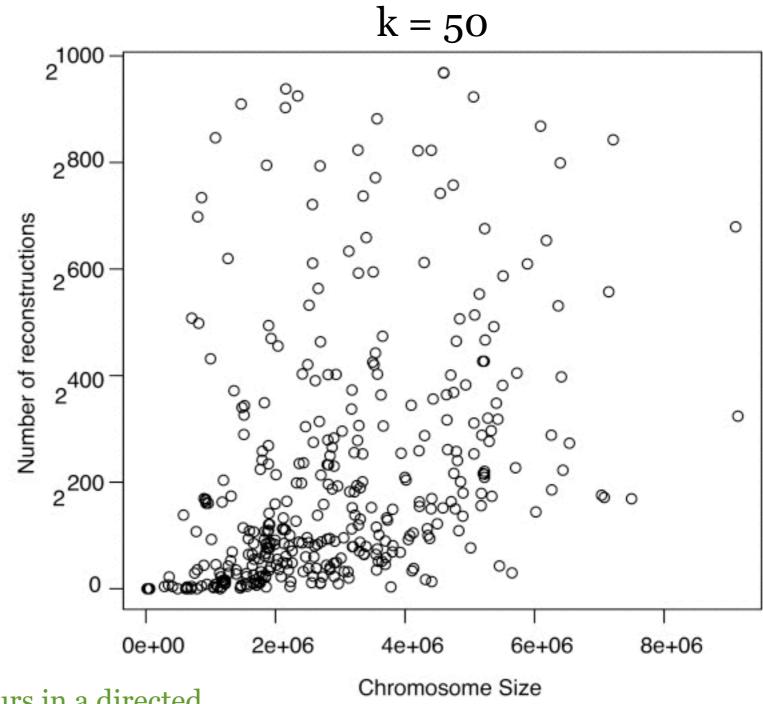
The Problem with Eulerian Paths

There are typically an astronomical number of possible Eulerian tours with perfect data.

Adding back constraints to limit # of tours leads to a NP-hard problem.

With imperfect data, there are usually NO Eulerian tours

Estimating # of parallel edges is usually tricky.

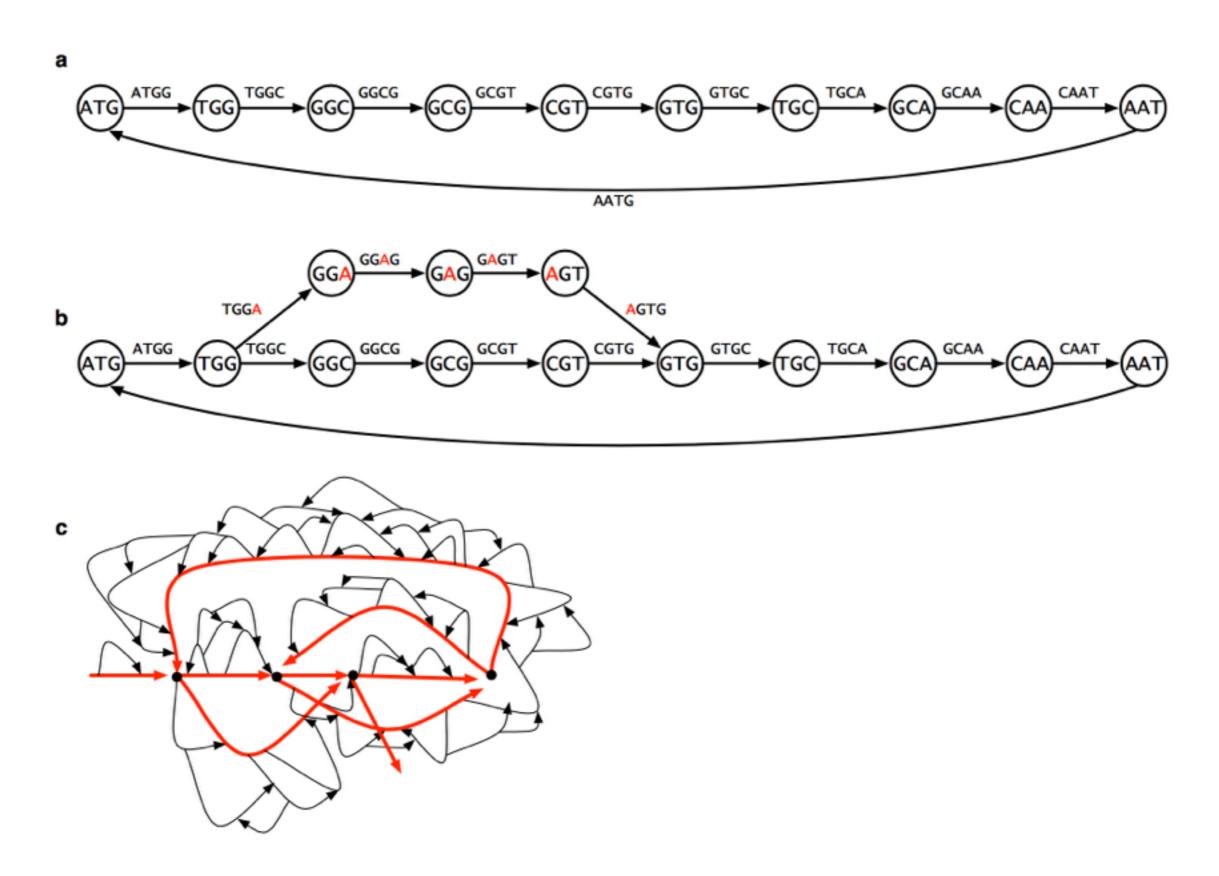


Aside: counting # of Eulerian tours in a directed graph is easy, but in an undirected graph is #P-complete (hard).

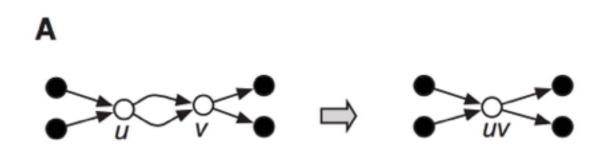
(Kingsford, Schatz, Pop, 2010)

^{*} slide courtesy of Carl Kingsford

Bursting bubbles



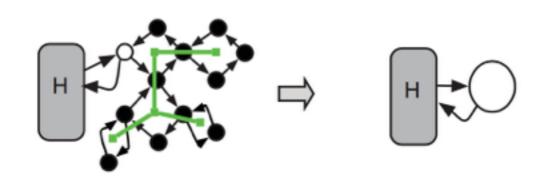
Other useful transformations



Path compression

collapse nodes u,v if v must follow u and u must precede v

Other useful transformations

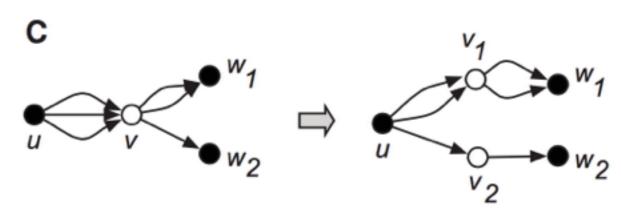


Compressing subtrees of the cycle graph

Trees in the cycle graph represent subgraphs with unique solutions, and can therefore be collapsed

Can obtain from G a cycle graph, **cycle**(G) (green above), where each vertex is a simple cycle and an edge connects two cycles if they share a node in the Eulerian graph G

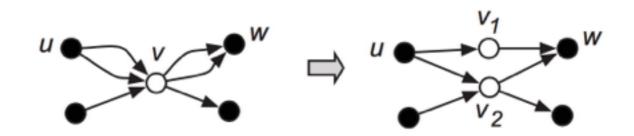
Other useful transformations



Splitting half decision nodes

"Half-decision" nodes (those with a single predecessor or successor) can be split into multiple nodes that can often be further compressed with path-compression

Other useful transformations

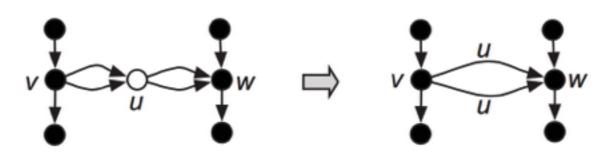


Exploiting edge multiplicities

Let $u \rightarrow v \rightarrow w$ be 3 nodes in a path s.t. $u \rightarrow v$ has the highest multiplicity of edges entering v and $v \rightarrow w$ has the highest multiplicity of edges laving v. Let $c_{u \rightarrow v}$ and $c_{v \rightarrow w}$ be multiplies of $u \rightarrow v$ and $v \rightarrow w$. If $u \neq w$, we can infer that $u \rightarrow v \rightarrow w$ must be part of any Eulerian tour if $c_{u \rightarrow v} > d^+(v) - c_{v \rightarrow w}$ where $d^+(v)$ is the out-degree of v.

(Kingsford, Schatz, Pop, 2010)

Other useful transformations



Converting non-decision nodes to edges

Replacing non-decision nodes with edges, along with the other transformations considered here, results in a graph containing either just a single node, or only decision nodes that have both more than one predecessor and more than on successor.

In practice, De Bruijn graph-based tools give up on unresolvable repeats and yield fragmented assemblies, just like OLC tools.

But first we note that using the De Bruijn graph representation has **other advantages**...

genome of length m

Say a sequencer produces
$$d = 6 \times 10^9 \text{ reads}$$
 $\approx 1 \text{ sequencing run}$ d reads of length $m = 100 \text{ nt}$ $m = 3 \times 10^9 \text{ nt} \approx 1 \text{ human}$

To build a De Bruijn graph in practice:

Pick k. Assume $k \le$ shortest read length (k = 30 to 50 is common).

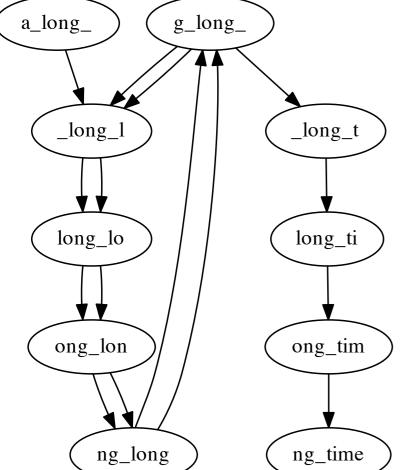
For each read:

For each *k*-mer:

Add k-mer's left and right k-1-mers to graph if not there already. Draw an edge from left to right k-1-mer.

long lon

ong long

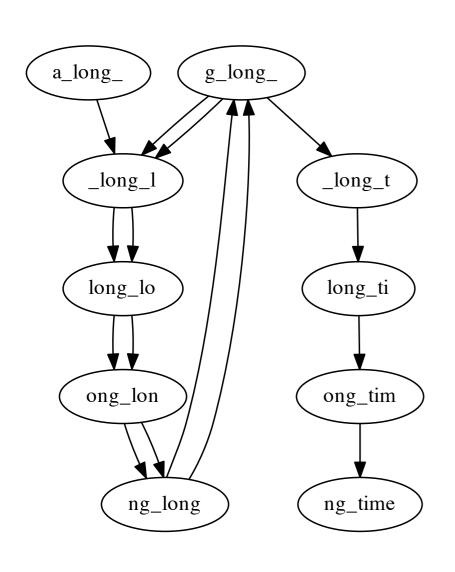


Given n (# reads), N (total length of all reads) and k, and assuming k < length of shortest read:

Exact number of k-mers: N - n(k-1) = O(N)

This is also the number of edges, |E|

Number of nodes |V| is at most $2 \cdot |E|$, but typically much smaller due to repeated k-1-mers



How much work to build graph?

For each k-mer, add 1 edge and up to 2 nodes

Reasonable to say this is O(1) expected work

Assume hash map encodes nodes & edges

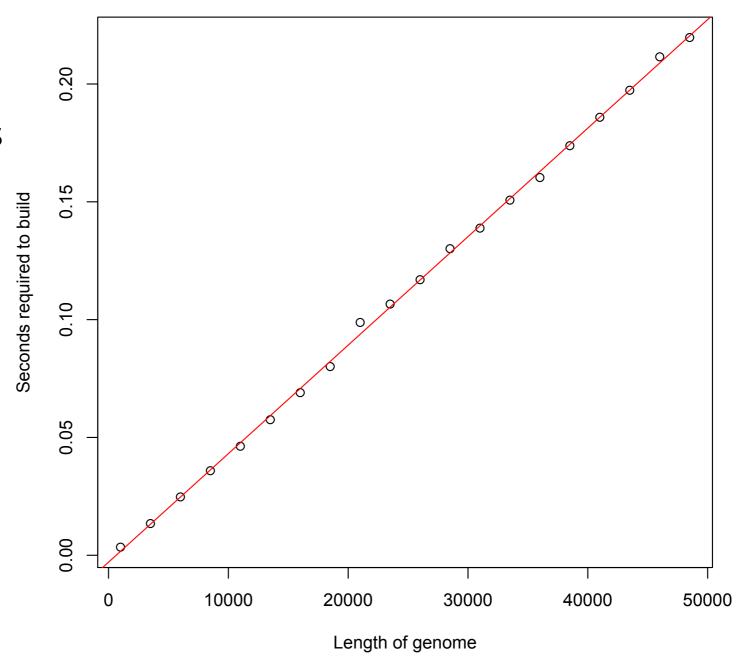
Assume k-1-mers fit in O(1) machine words, and hashing O(1) machine words is O(1) work

Querying / adding a key is O(1) expected work

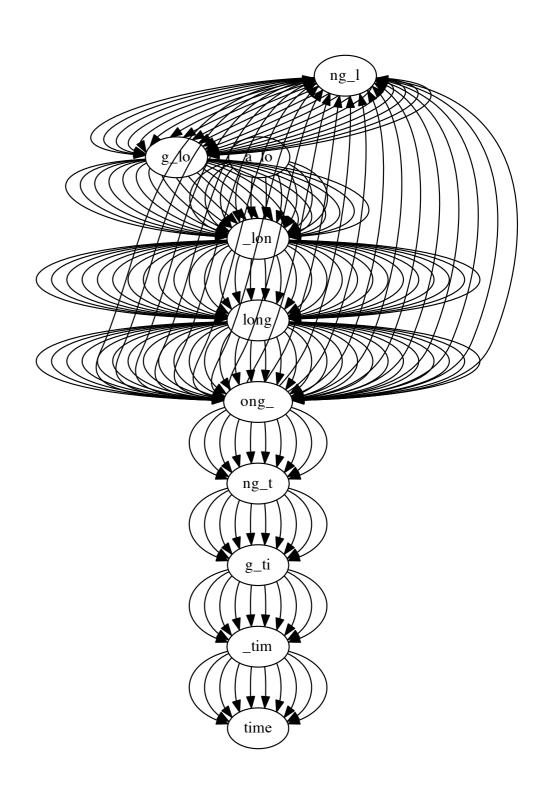
O(1) expected work for 1 k-mer, O(N) overall

Timed De Bruijn graph construction applied to progressively longer prefixes of lambda phage genome, k = 14

O(N) expectation appears to work in practice, at least for this small example



In typical assembly projects, average coverage is ~ 30 - 50



Recall average coverage: average # reads covering a genome position

CTAGGCCCTCAATTTTT

CTCTAGGCCCTCAATTTTT

GGCTCTAGGCCCTCATTTTT

CTCGGCTCTAGCCCCTCATTTT

TATCTCGACTCTAGGCCCTCA

TATCTCGACTCTAGGCC

TCTATATCTCGGCTCTAGG

GGCGTCTATATCTCG

GGCGTCGATATCT

GGCGTCTATATCT

GGCGTCTATATCTCGGCTCTAGGCCCTCATTTTTT

177 nucleotides

35 nucleotides

Average coverage = $177 / 35 \approx 7x$

In typical assembly projects, average coverage is ~ 30 - 50

Same edge might appear in dozens of copies; let's use edge weights instead

Weight = # times *k*-mer occurs

Using weights, there's one weighted edge for each distinct k-mer

After: one weighted _tim edge per *distinct k*-mer

Before: one edge per k-mer

of nodes and edges both O(N); N is total length of all reads

Say (a) reads are error-free, (b) we have one *weighted* edge for each *distinct k*-mer, and (c) length of genome is *G*

There's one node for each distinct *k*-1-mer, one edge for each distinct *k*-mer

Can't be more distinct k-mers than there are k-mers in the genome; likewise for k-1-mers

So # of nodes and edges are also both O(G)

Combine with the O(N) bound and the # of nodes and edges are both $O(\min(N, G))$

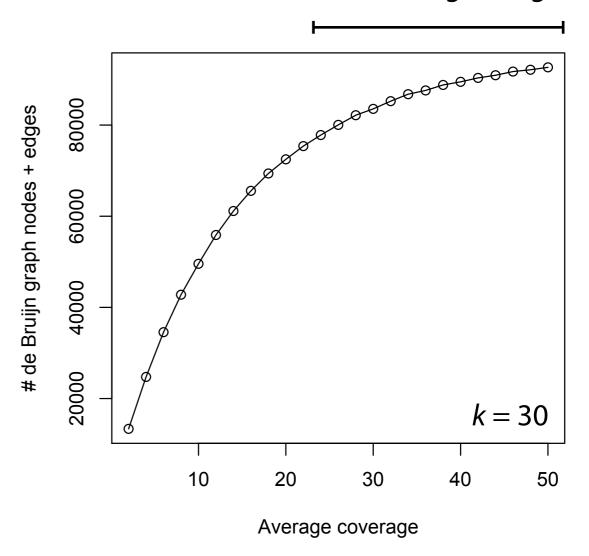
With high average coverage, O(G) size bound is advantageous

Genome = lambda phage (~ 48.5 K nt)

Draw random *k*-mers until target average coverage is reached (x axis)

Build De Bruijn graph and total the # of nodes and edges (y axis)

Size of De Bruijn graph grows sublinearly when average coverage is high



What De Bruijn graph advantages have we discovered?

Can be built in O(N) expected time, N = total length of reads

With perfect data, graph is $O(\min(N, G))$ space; G = genome length

Note: when average coverage is high, $G \ll N$

Compares favorably with overlap graph

Space is O(N + a).

Fast overlap graph construction (suffix tree) is O(N + a) time a is $O(n^2)$

What did we give up?

Reads are immediately split into shorter *k*-mers; can't resolve repeats as well as overlap graph

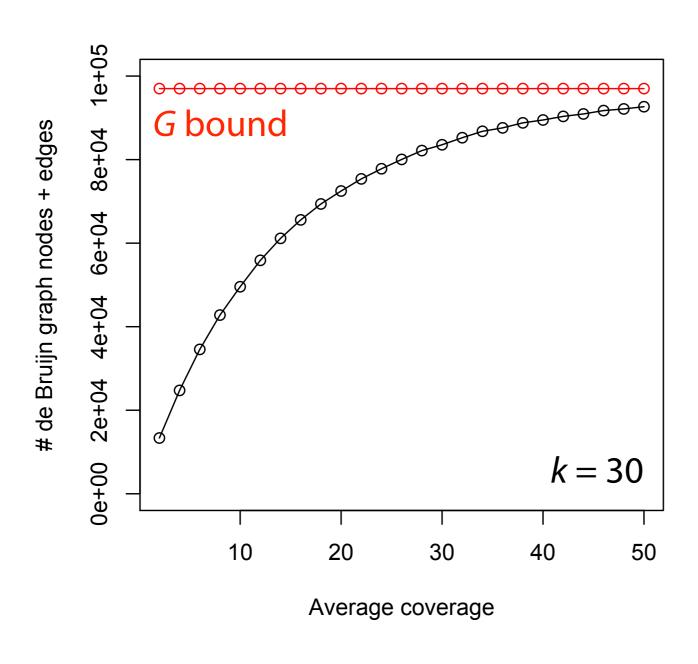
Only a very specific type of "overlap" is considered, which makes dealing with errors more complicated, as we'll see

Read coherence is lost. Some paths through De Bruijn graph are inconsistent with respect to input reads.

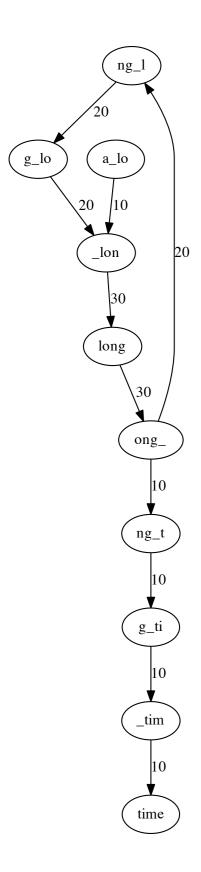
This is the OLC \leftrightarrow DBG tradeoff

Single most important benefit of De Bruijn graph is the $O(\min(G, N))$ space bound, though we'll see this comes with large caveats

When data is error-free, # nodes, edges in de Bruijn graph is O(min(G, N))

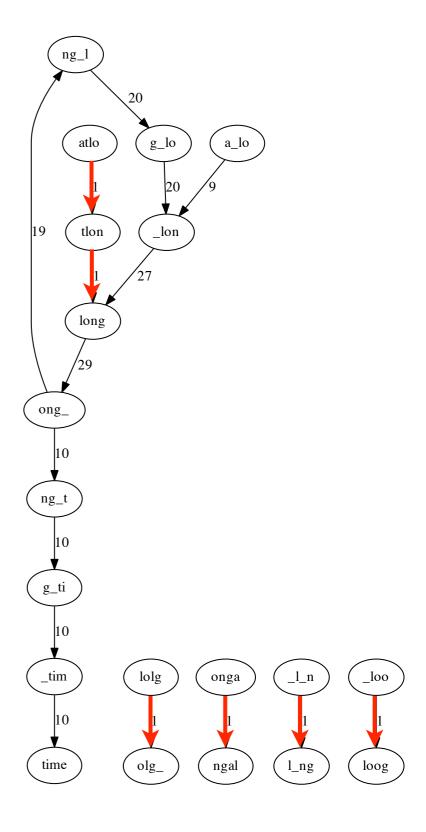


What about data with sequencing errors?

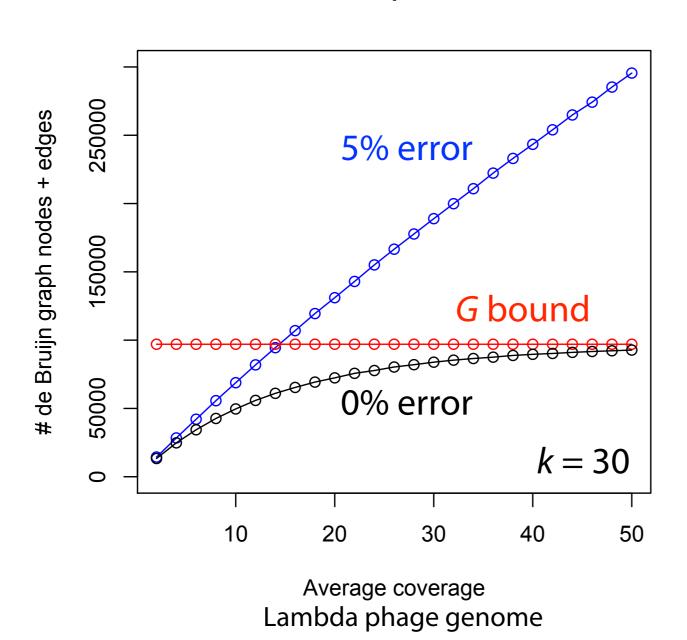


Take an example we saw (left) and mutate a *k*-mer character to a random other character with probability 1% (right)

6 errors result in 10 new nodes and 6 new weighted edges, all with weight 1



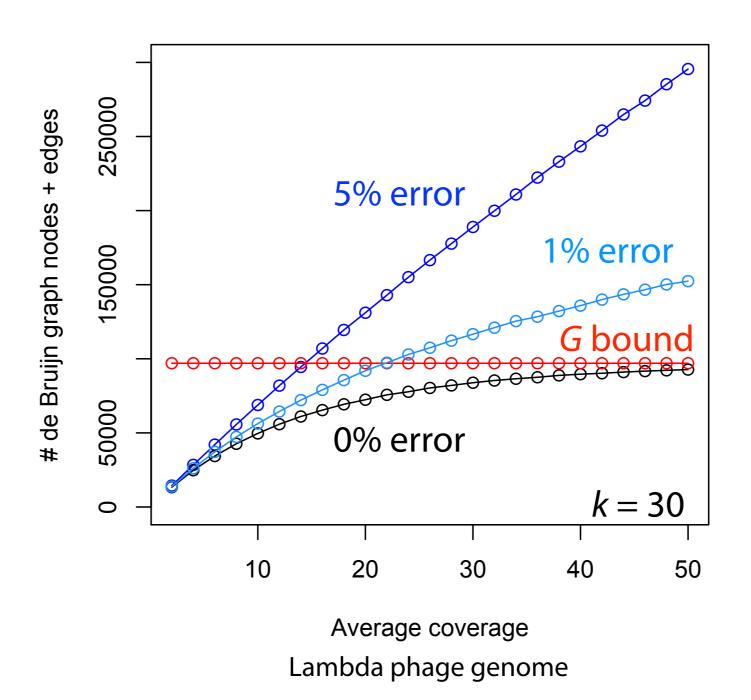
As more k-mers overlap errors, # nodes, edges approach N



Same experiment as before but with 5% error added

Errors wipe out much of the benefit of the *G* bound

Instead of $O(\min(G, N))$, we have something more like O(N)



If we can correct sequencing errors up-front, we can prevent De Bruijn graph from growing much beyond the *G* bound

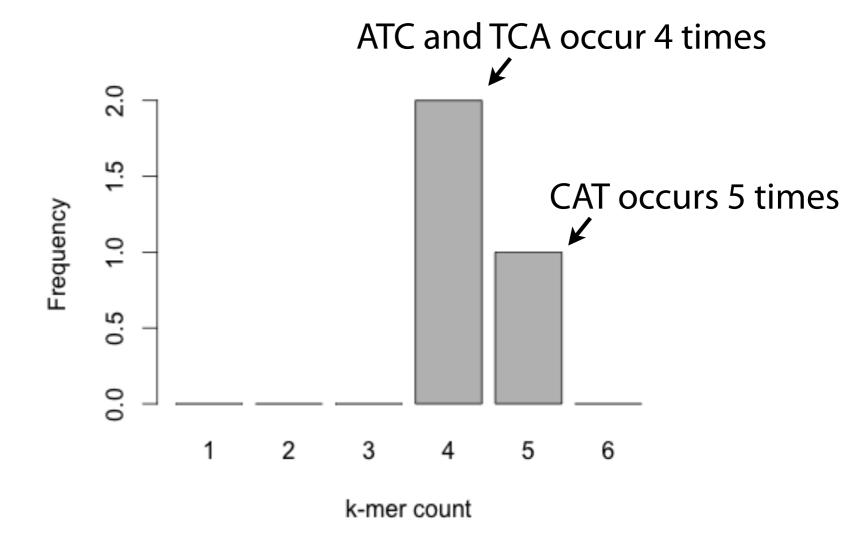
How do we correct errors?

Analogy: design a spell checker for a language you've never seen before. How do you come up with suggestions?

k-mer count histogram:

x axis is an integer k-mer count, y axis is # distinct k-mers with that count

Right: such a histogram for 3-mers of CATCATCATCATCAT:

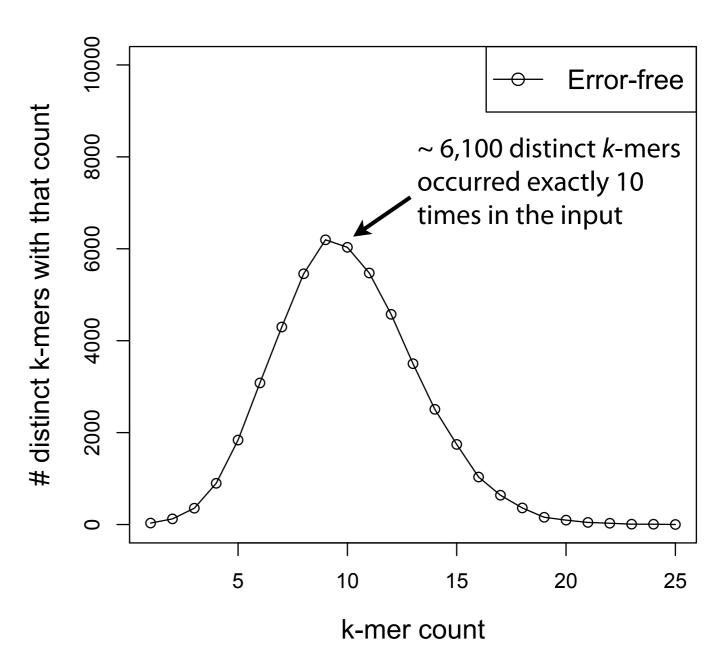


Say we have error-free sequencing reads drawn from a genome. The amount of sequencing is such that average coverage = 200.

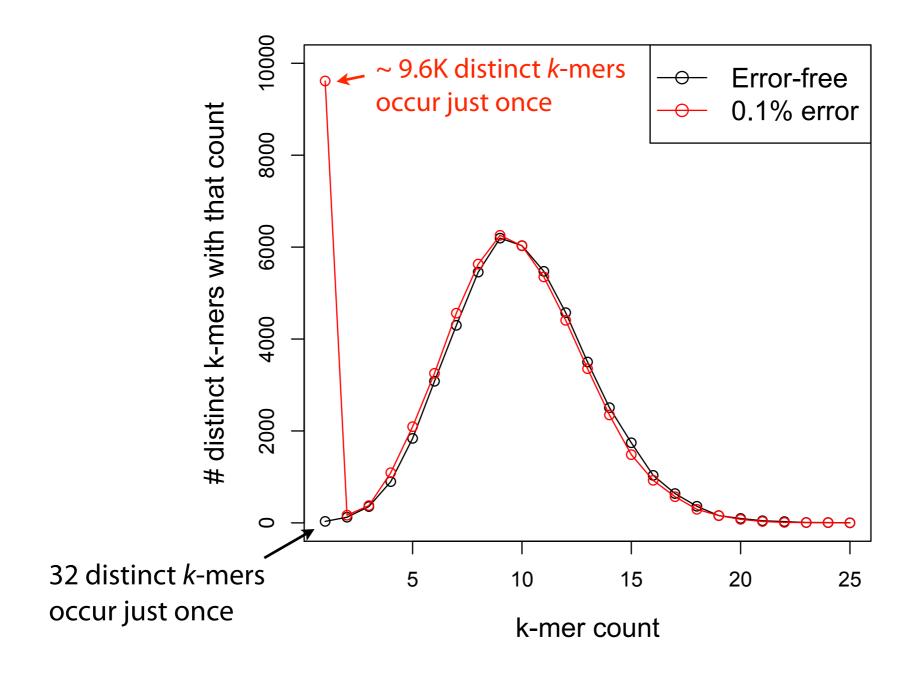
Let k = 20

How would the picture change for data with 1% error rate?

Hint: errors usually change high-count *k*-mer into low-count *k*-mer



k-mers with errors usually occur fewer times than error-free *k*-mers



Idea: errors tend to turn frequent k-mers to infrequent k-mers, so corrections should do the reverse

Say we have a collection of reads where each distinct 8-mer occurs an average of ~10 times, and we have the following read:

```
Read:
                                     (20 nt)
         GCGTATTACGCGTCTGGCCT
          GCGTATTA: 8
           CGTATTAC: 8
            GTATTACG: 9
             TATTACGC: 9
                                   # times each 8-mer
              ATTACGCG: 9
                                   occurs in the dataset.
                TTACGCGT: 12
                                   "k-mer count profile"
                 TACGCGTC: 9
     8-mers:
                  ACGCGTCT: 8
                   CGCGTCTG: 10
                                              All 8-mer counts are around
                    GCGTCTGG: 10
                                              the average, suggesting read
                     CGTCTGGC: 11
                      GTCTGGCC: 9
                                              is error-free
```

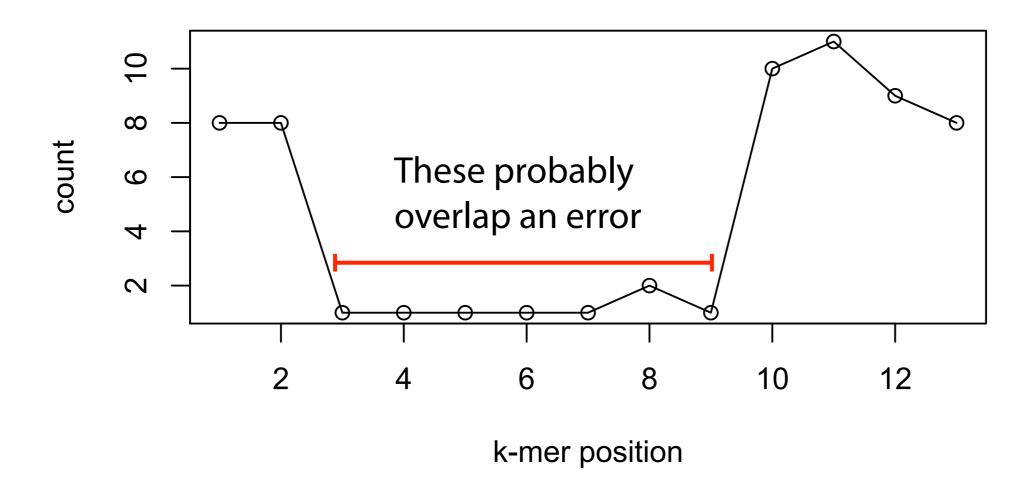
Suppose there's an error

```
Read:
        GCGTACTACGCGTCTGGCCT
        GCGTACTA: 1
                                            k-mer count profile has
          CGTACTAC: 3
                            Below average
                                            corresponding stretch of
           GTACTACG: 1
                                            below-average counts
            TACTACGC: 1
             ACTACGCG: 2
              CTACGCGT: 1
               TACGCGTC: 9
                ACGCGTCT: 8
                 CGCGTCTG: 10
                                     Around average
                  GCGTCTGG: 10
                   CGTCTGGC: 11
                    GTCTGGCC: 9
                      TCTGGCCT: 8
```

k-mer count profiles when errors are in different parts of the read:

GCGTACTACGCGTCTGGCCT GCGTATTACACGTCTGGCCT GCGTATTACGCGTCTGGTCT GCGTACTA: 1 GCGTATTA: 8 GCGTATTA: 8 CGTATTAC: 8 CGTACTAC: 3 CGTATTAC: 8 GTACTACG: 1 GTATTACA: 1 GTATTACG: 9 TACTACGC: 1 TATTACAC: 1 TATTACGC: 9 ACTACGCG: 2 ATTACACG: 1 ATTACGCG: 9 CTACGCGT: 1 TTACACGT: 1 TTACGCGT: 12 TACGCGTC: 9 TACACGTC: 1 TACGCGTC: 9 ACGCGTCT: 8 ACACGTCT: 2 ACGCGTCT: 8 CGCGTCTG: 10 CACGTCTG: 1 CGCGTCTG: 10 GCGTCTGG: 10 GCGTCTGG: 10 GCGTCTGG: 10 CGTCTGGC: 11 CGTCTGGC: 11 CGTCTGGT: 1 GTCTGGCC: 9 GTCTGGCC: 9 GTCTGGTC: 2 TCTGGCCT: 8 TCTGGCCT: 8 TCTGGTCT: 1

k-mer count profile indicates where errors are



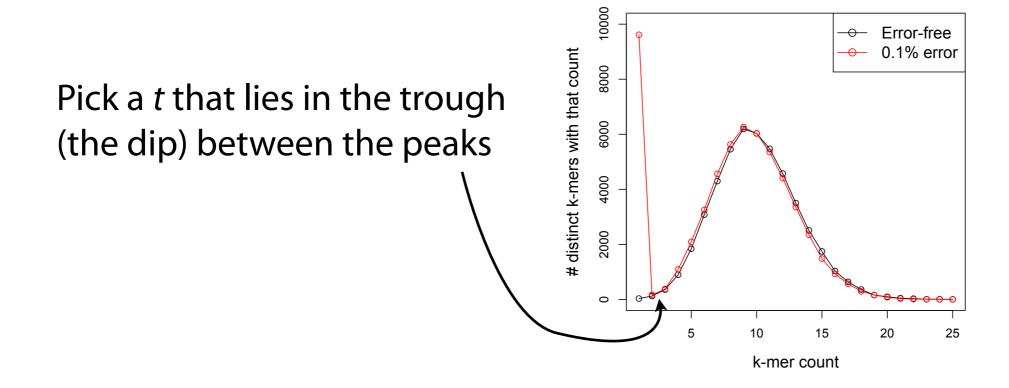
Simple algorithm: given a count threshold *t*:

For each read:

For each k-mer:

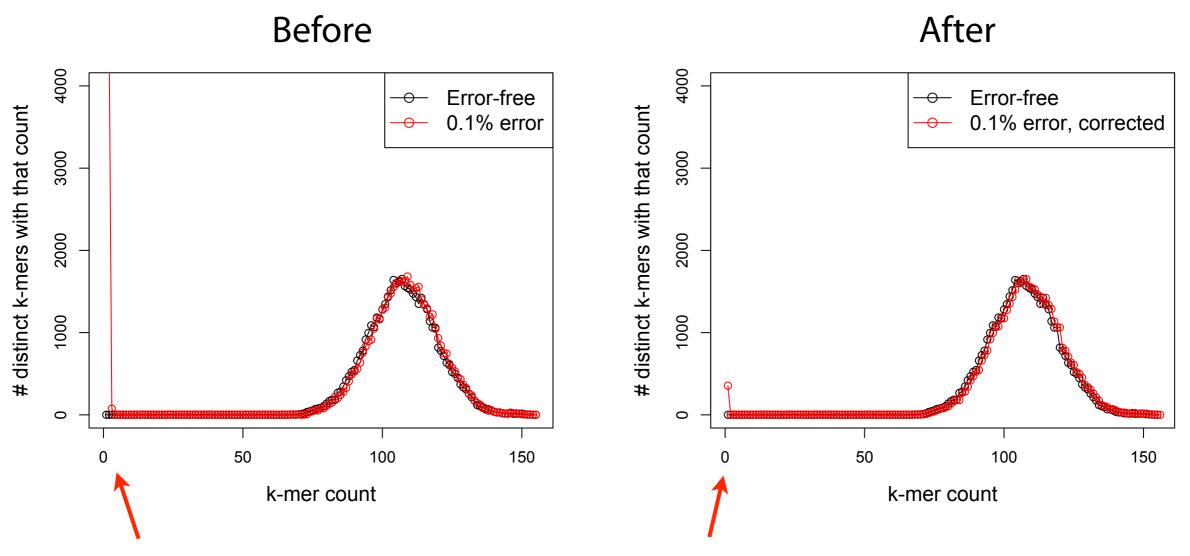
If *k*-mer count < *t*:

Examine k-mer's neighbors within certain Hamming/edit distance. If neighbor has count $\geq t$, replace old k-mer with neighbor.



Error correction: results

Corrects 99.2% of the errors in the example 0.1% error dataset

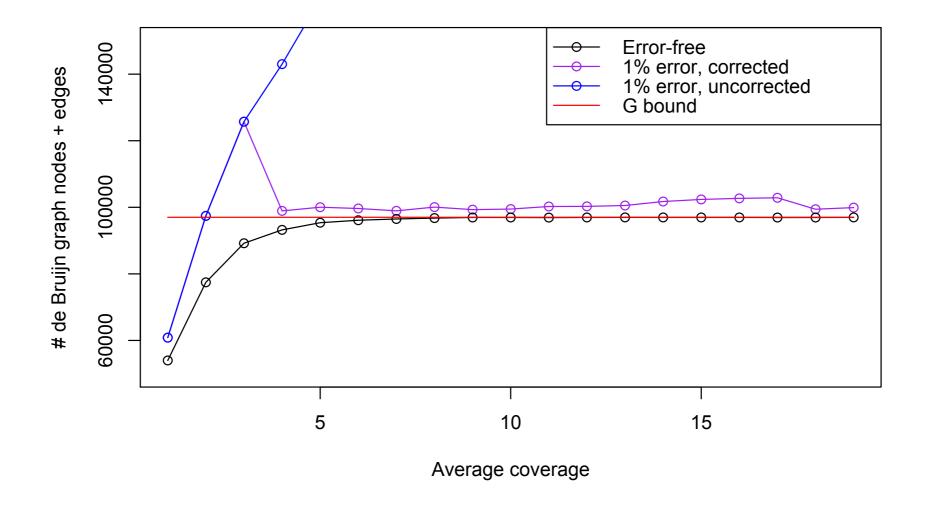


From 194K k-mers occurring exactly once to just 355

Error correction: results

For uncorrected reads, De Bruijn graph size is off the chart

For corrected reads, De Bruijn graph size is near G bound



For error correction to work well:

Average coverage should be high enough and *k* should be set so we can distinguish infrequent from frequent *k*-mers

k-mer neighborhood we explore must be broad enough to find frequent neighbors. Depends on error rate and k.

Data structure for storing k-mer counts should be substantially smaller than the De Bruijn graph

Otherwise there's no point doing error correction separately

Counts don't have to be 100% accurate; just have to distinguish frequent and infrequent