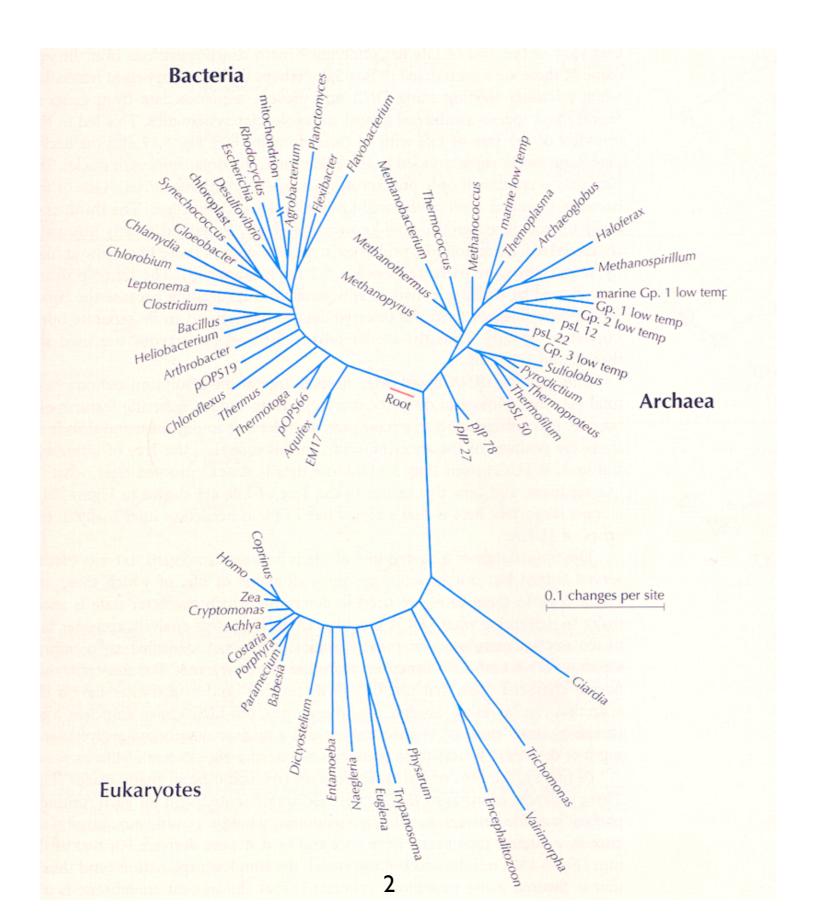
CSE 549: Computational Biology

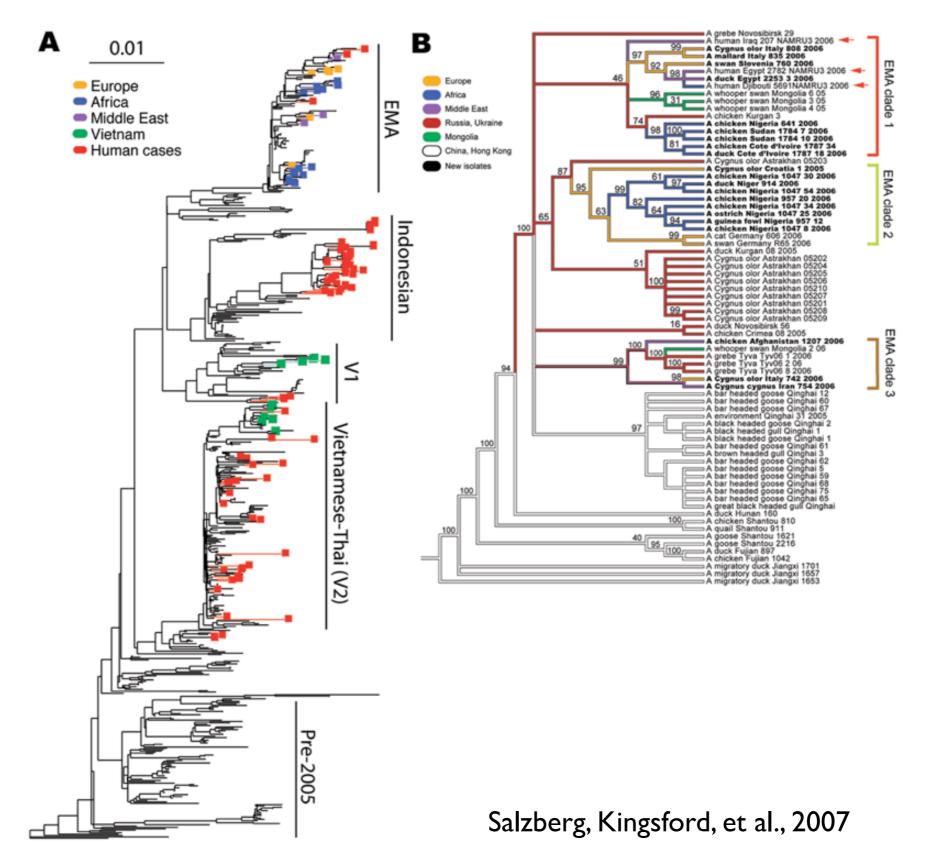
Phylogenomics



Tree of Life

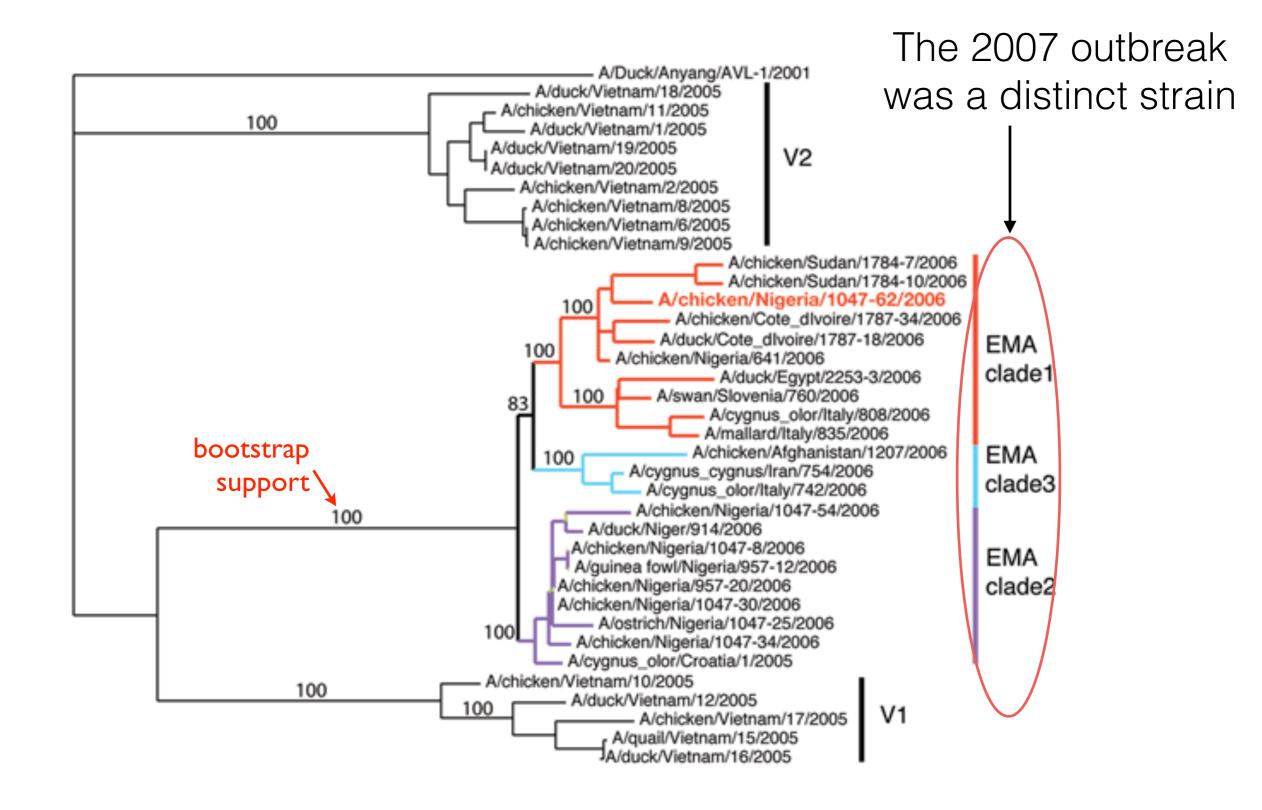


H5N1 Influenza Strains



3

H5N1 Influenza Strains



Questions Addressable by Phylogeny

- How many times has a feature arisen? been lost?
- How is a disease evolving to avoid immune system?
- What is the sequence of ancestral proteins?
- What are the most similar species?
- What is the rate of speciation?
- Is there a correlation between gain/loss of traits and environment? with geographical events?
- Which features are ancestral to a clade, which are derived?
- What structures are homologous, which are analogous?

Study Design Considerations

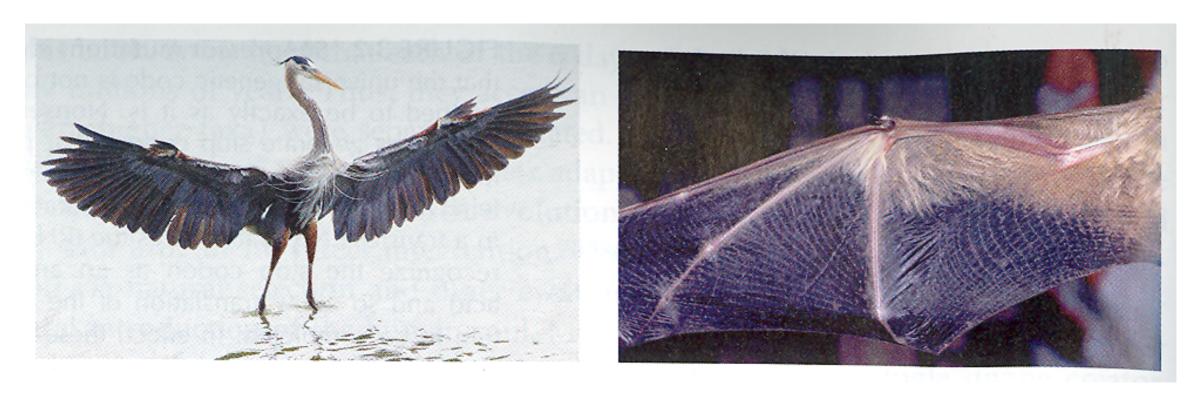
• Taxon sampling:

- how many individuals are used to represent a species?
- how is the "outgroup" chosen?
- Can individuals be collected or cultured?

Marker selection: Sequence features should:

- be Representative of evolutionary history (unrecombined)
- have a single copy
- be able to be amplified using PCR
- able to be sequenced
- change enough to distinguish species, similar enough to perform MSA

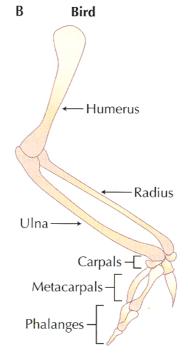
Convergent Evolution

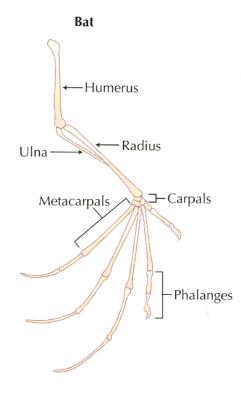


Bird & bat wings arose independently (analogous)

"Has wings" is thus a "bad" trait for phylogenetic inference

Bone structure has common ancestor (homologous)

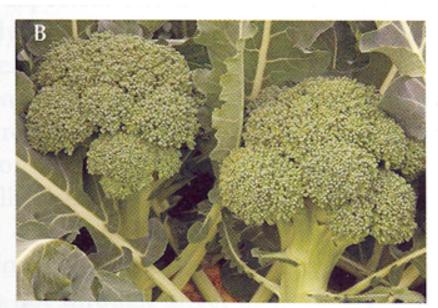




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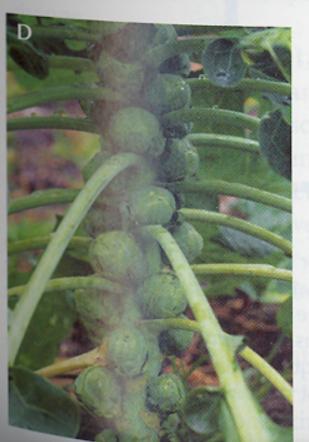
"Divergent" Evolution

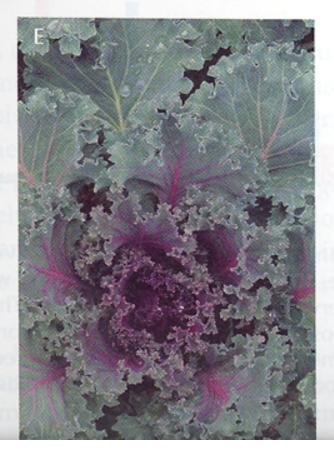




8







"Obvious" phenotypic traits are not necessarily good markers

These are all one species!

FIGURE 3.7. Diverse varieties of *Brassica oleracea* include (*A*) cabbage; (*B*) broccoli; (*C*) cauliflower; (*D*) brussels sprouts; and (*E*) flowering kale.

Two phylogeny "problems"

Note: "Character" below is not a letter (e.g. A,C,G,T), but a particular characteristic under which we consider the phylogeny (e.g. column of a MSA). Each character takes on a *state* (e.g. A,C,G,T).

The **small** phylogeny problem

Given: a set of characters at the leaves (extant species), a set of states for each character, the cost of transition from each state to every other, and the *topology* of the phylogenetic tree

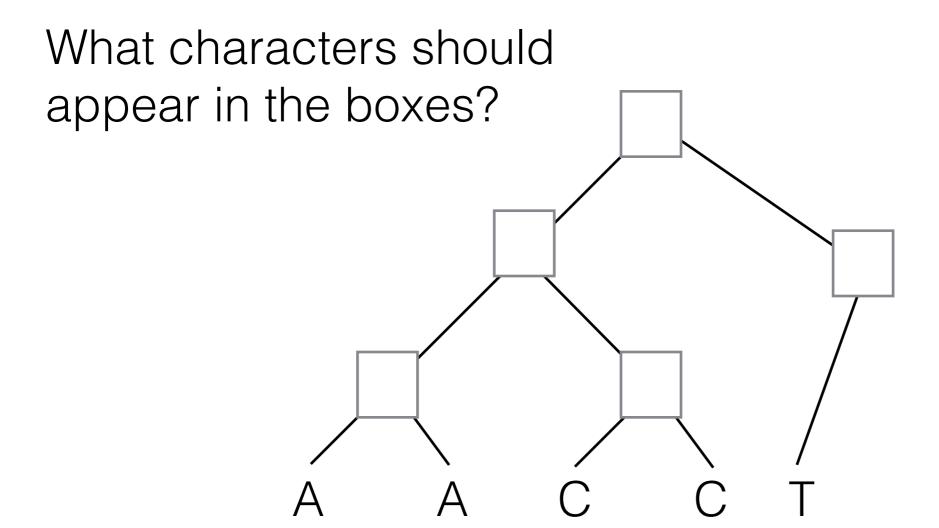
Find: a labeling for each internal node that minimizes the *overall* cost of transitions.

The large phylogeny problem

Given: a set of characters at the leaves (extant species), a set of states for each character, the cost of transition from each state to every other

Find: a tree topology and labeling for each internal node that minimizes the *overall* cost (over all trees and internal states)

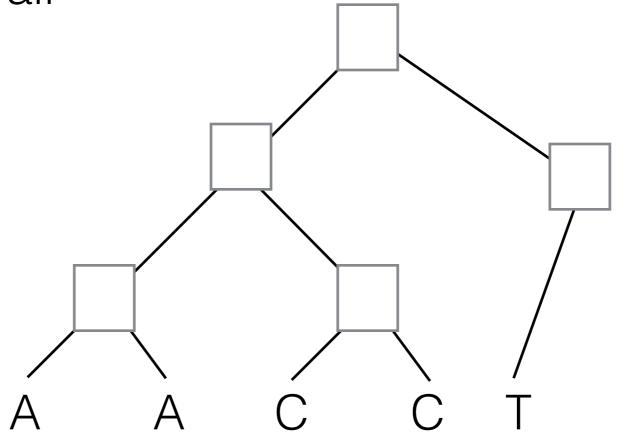
One way to define the lowest *cost* set of transitions is to maximize *parsimony*. That is, posit as few transitions as necessary to produce the observed result.



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Assume transitions all have unit cost:

	A	С	G	Т
Α	0	1	1	1
С	1	0	1	1
G	1	1	0	1
Т	1	1	1	0

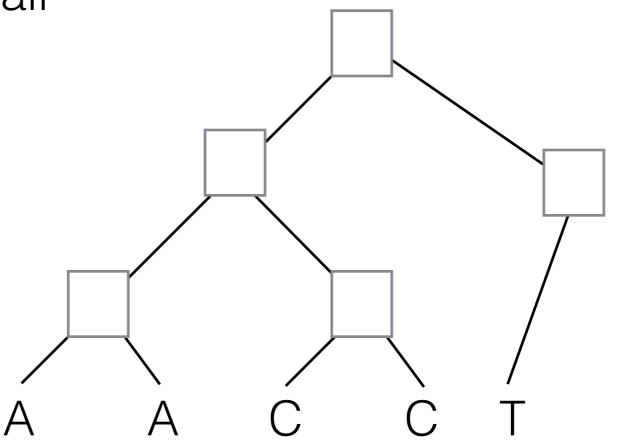


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Fitch's algorithm provides a solution.



Fitch's algorithm (2-pass):

Visit nodes in *post-order* traversal:

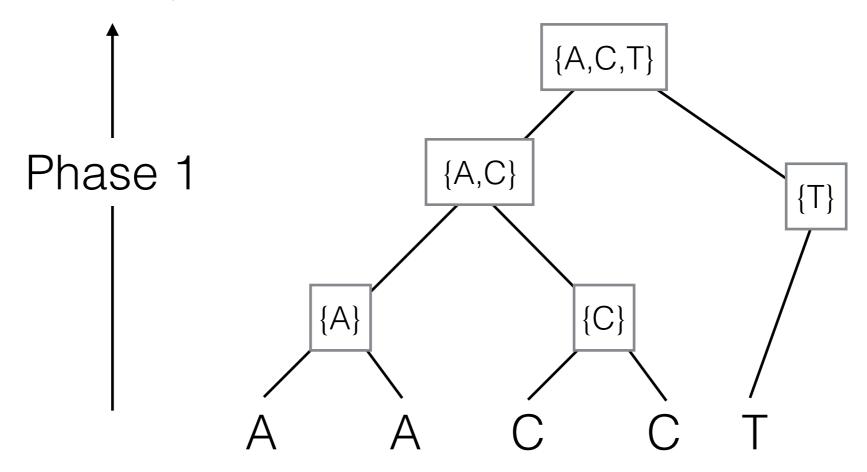
store a set of characters at each node

take the intersection of child's set if not empty; else take the union

Visit nodes in *pre-order* traversal:

If a child's character set has it's parent's label, choose it.

Otherwise, select any character in this node's character set.



Fitch's algorithm (2-pass):

Visit nodes in *post-order* traversal:

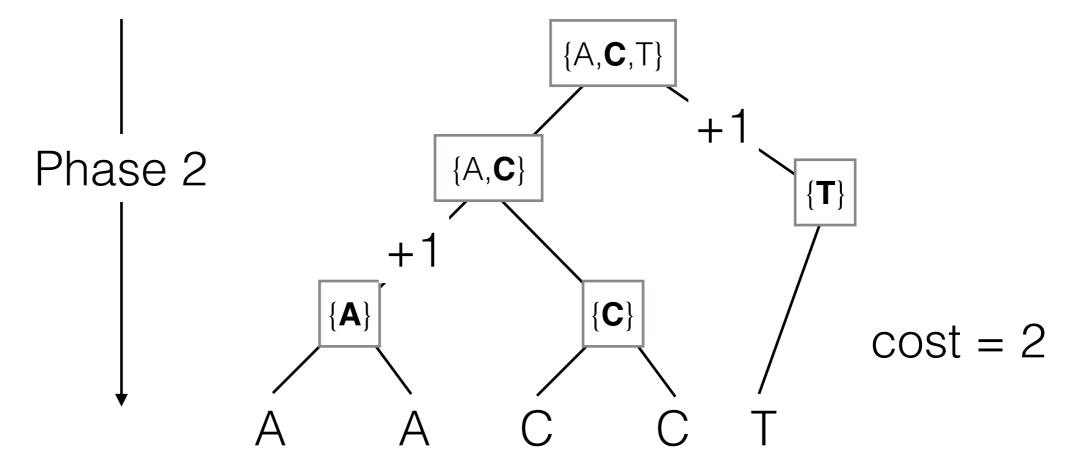
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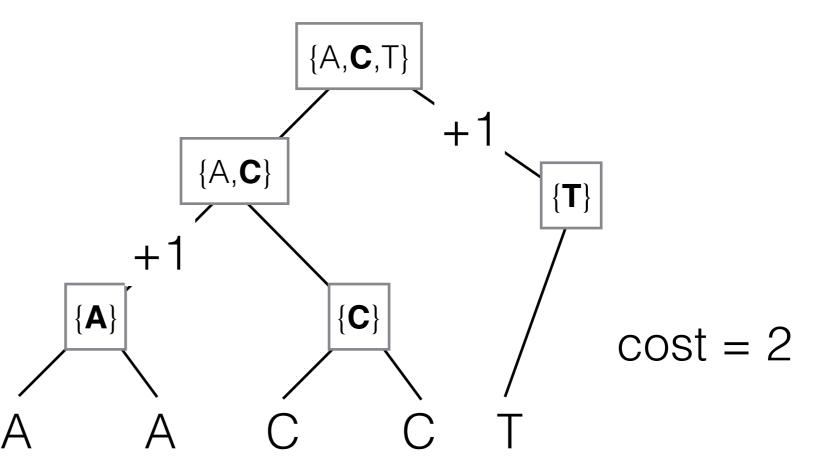
take the intersection of child's set if not empty; else take the union

Visit nodes in *pre-order* traversal:

If a child's character set has it's parent's label, choose it.

Otherwise, select any character in this node's character set.

Note: There are generally many solutions of optimal cost.



What if there are different costs for each transition? Sankoff* provides a dynamic program to solve this case.

For simplicity, consider only a single character, c

Phase 1 (post-order):

For each leaf v, state t, let
$$S_t^c(v) = \begin{cases} 0 & \text{if } v_c = t \\ \infty & \text{otherwise} \end{cases}$$

For each internal v, state t, let $S_t^c(v) = \min_i \left\{ C_{ti}^c + S_i^c(u) \right\} + \min_i \left\{ C_{tj}^c + S_j^c(w) \right\}$

Phase 2 (pre-order):

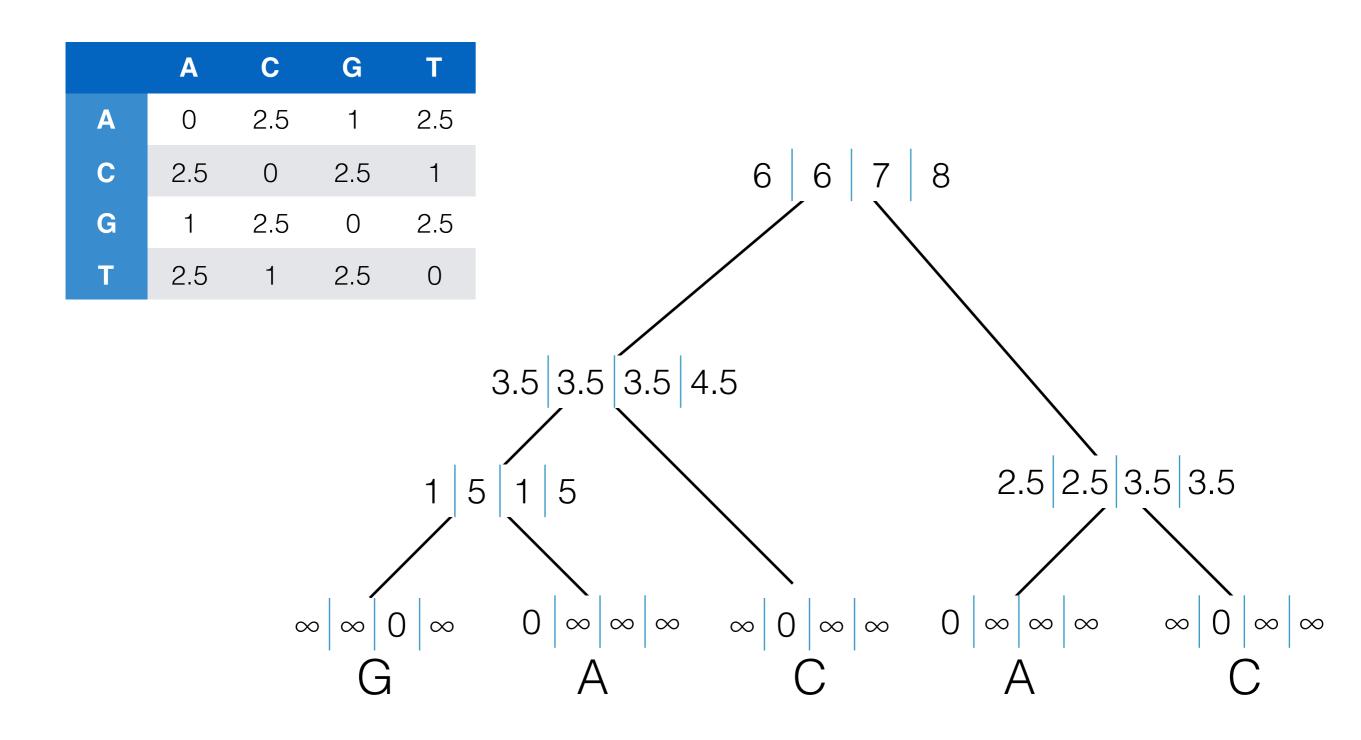
Let the root take state $r_c = \arg\min_t S_t^c(r)$

For all other v with parent u, let: $v_c = \arg\min_t \left(C_{u_ct}^c + S_t^c(v)\right)$

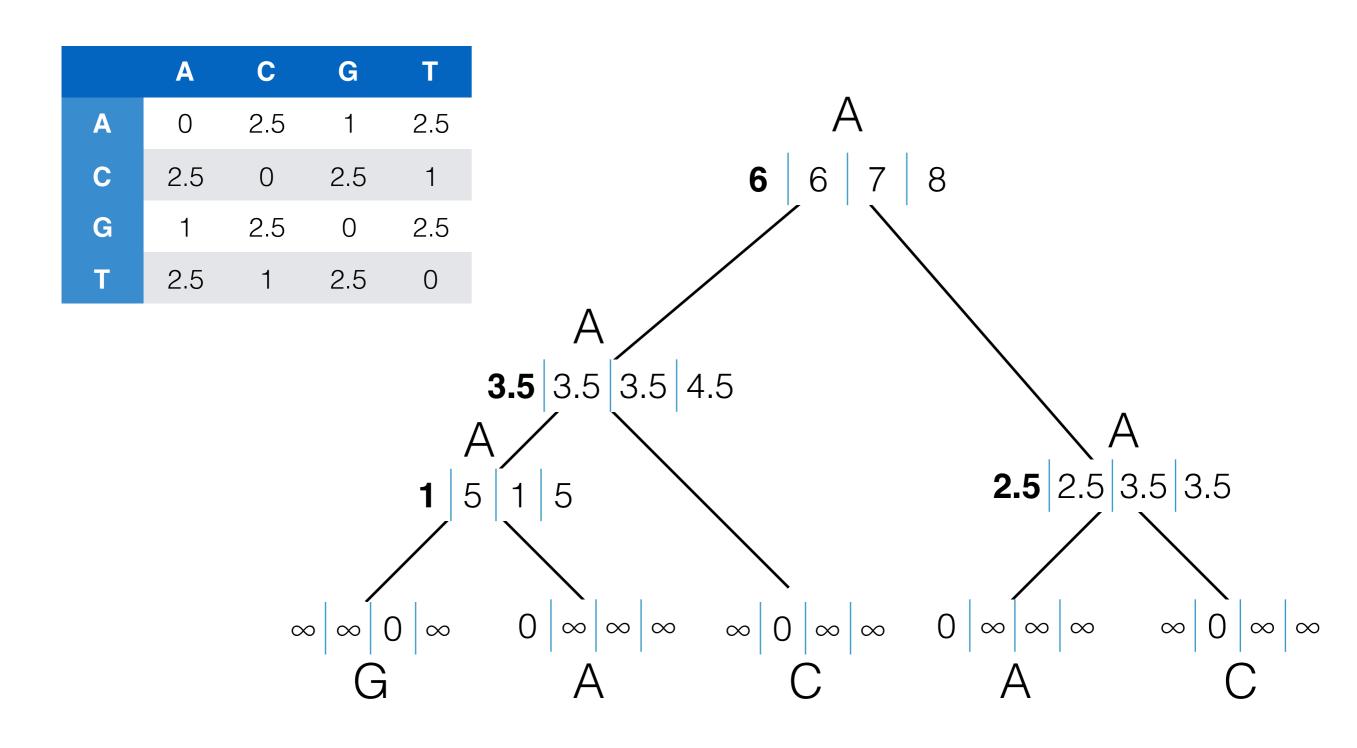
Choose the best parent states.

Choose the best child states given the parent states chosen above

Consider the following tree and transition matrix:

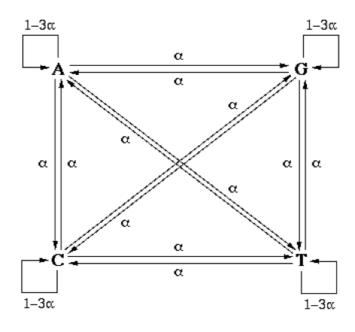


Consider the following tree and transition matrix:



Imagine we assume a specific, probabilistic model of sequence evolution. For example:

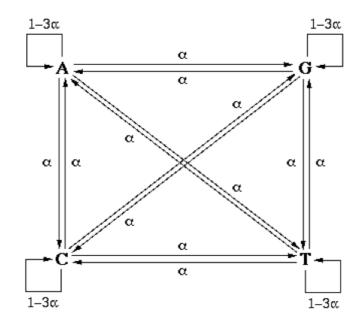
Jukes-cantor



α is the probability to mutate (per-unit time)

Imagine we assume a specific, probabilistic model of sequence evolution. For example:

Jukes-cantor



 α is the probability to mutate (per-unit time)

or General Time Reversible

Time reversible:

Base frequencies:

$$\pi_i Q_{ij} = \pi_j Q_{ji}$$

$$\Pi = (\pi_T, \pi_C, \pi_A, \pi_G)$$

Rate matrix (per unit time):

$$Q = egin{pmatrix} -(lpha\pi_C + eta\pi_A + \gamma\pi_G) & lpha\pi_C & eta\pi_A & \gamma\pi_G \ lpha\pi_T & -(lpha\pi_T + \delta\pi_A + \epsilon\pi_G) & \delta\pi_A & \epsilon\pi_G \ eta\pi_T & \delta\pi_C & -(eta\pi_T + \delta\pi_C + \eta\pi_G) & \eta\pi_G \ \gamma\pi_T & \epsilon\pi_C & \eta\pi_A & -(\gamma\pi_T + \epsilon\pi_C + \eta\pi_A) \end{pmatrix}$$

Transition matrix at time t:

$$P(t) = e^{Qt} = \sum_{n=0}^{\infty} Q^n \frac{t^n}{n!}$$

$$lpha = r(T
ightarrow C) = r(C
ightarrow T) \ eta = r(T
ightarrow A) = r(A
ightarrow T) \ \gamma = r(T
ightarrow G) = r(G
ightarrow T) \ \delta = r(C
ightarrow A) = r(A
ightarrow C) \ \epsilon = r(C
ightarrow G) = r(G
ightarrow C) \ \eta = r(A
ightarrow G) = r(G
ightarrow A)$$

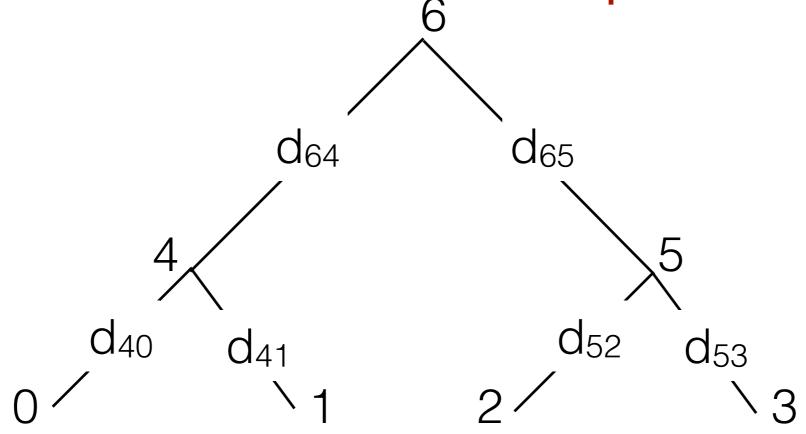
Imagine we assume a specific, probabilistic model of sequence evolution.

Given a tree topology (with branch lengths), a set of states for each character, and the assumed model of state evolution

Find the states at each internal node that *maximizes* the likelihood of the observed data (i.e. states at the leaves)

Rather than choosing the *best* state at each site, we are summing over the possibility of *all* states (phylogenetic histories)

Consider the simple tree

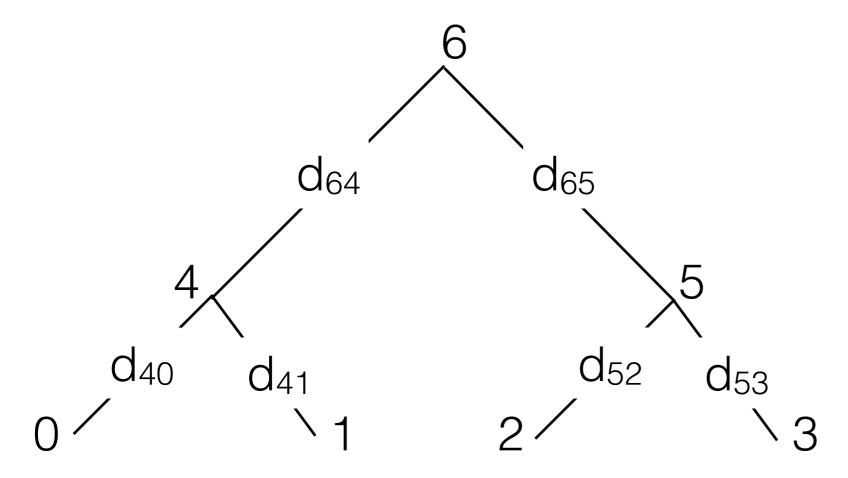


For particular ancestral states s₆, s₄ and s₅, we can score their likelihood as:

$$\tilde{\mathcal{L}}(s_6, s_4, s_5) = p_{s_6 \to s_4}(d_{64}) \cdot p_{s_6 \to s_5}(d_{65}) \cdot p_{s_4 \to s_0}(d_{40}) \cdot p_{s_4 \to s_1}(d_{41}) \cdot p_{s_5 \to s_2}(d_{52}) \cdot p_{s_5 \to s_3}(d_{53})$$

Since we don't know these states, we must *sum over* them:

$$\mathcal{L} = \sum_{s_6} \sum_{s_4} \sum_{s_5} \pi_{s_6} \tilde{\mathcal{L}}(s_6, s_4, s_5)$$

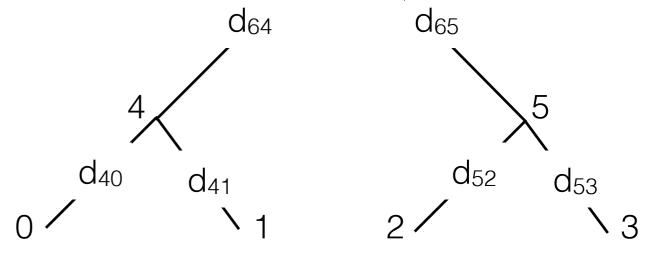


It turns out that this objective (maximum likelihood) can also be optimized in polynomial time.

This is done by re-arranging the terms and expressing them as conditional probabilities.

The algorithm is due to Felsenstein* — again, it is a dynamic program

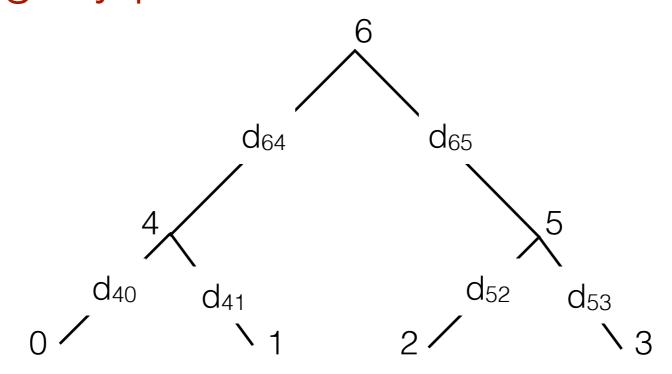
Idea 1: Re-arrange the computation to be more favorable



$$\mathcal{L} = \sum_{s_6} \sum_{s_4} \sum_{s_5} \pi_{s_6} \tilde{\mathcal{L}}(s_6, s_4, s_5)$$

via. Horner's method (push summations to the right)

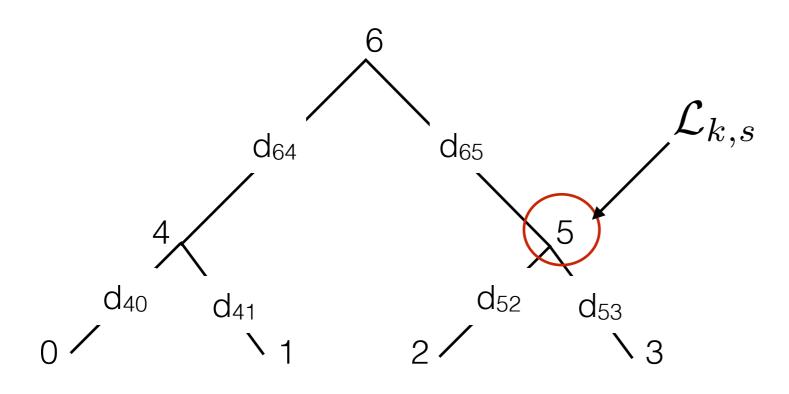
$$= \sum_{s_6} \pi_{s_6} \times \left\{ \begin{array}{l} \sum_{s_4} p_{s_6 \to s_4} d(s_{64}) \left(p_{s_4 \to s_0} d(s_{40}) p_{s_4 \to s_1} d(s_{41}) \right) \\ \times \\ \sum_{s_5} p_{s_6 \to s_5} d(s_{65}) \left(p_{s_5 \to s_2} d(s_{52}) p_{s_5 \to s_3} d(s_{53}) \right) \end{array} \right\}$$



$$\sum_{s_6} \pi_{s_6} \times \left\{ \begin{array}{l} \sum_{s_4} p_{s_6 \to s_4} d(s_{64}) \left(p_{s_4 \to s_0} d(s_{40}) p_{s_4 \to s_1} d(s_{41}) \right) \\ \times \\ \sum_{s_5} p_{s_6 \to s_5} d(s_{65}) \left(p_{s_5 \to s_2} d(s_{52}) p_{s_5 \to s_3} d(s_{53}) \right) \end{array} \right\}$$

The structure of the equations here matches the structure of the tree ((.,.)(.,.)) — see e.g. nested parenthesis encoding of trees.

Idea 2: define the total likelihood in terms of *conditional* likelihoods.



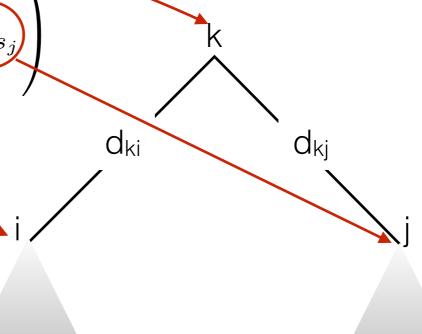
Conditional likelihood of the *subtree rooted at k*, assuming *k takes on states s.*

Now, we can define likelihood recursively!

$$\mathcal{L}_{k,s} = \Pr(s_k = s)$$
 if k is a leaf

$$\mathcal{L}_{k,s} = \left(\sum_{s_i} p_{s_k \to s_i}(d_{ki}) \mathcal{L}_{i,s_i}\right) \left(\sum_{s_j} p_{s_k \to s_j}(d_{kj}) \mathcal{L}_{j,s_j}\right)$$

... how can we do this efficiently?



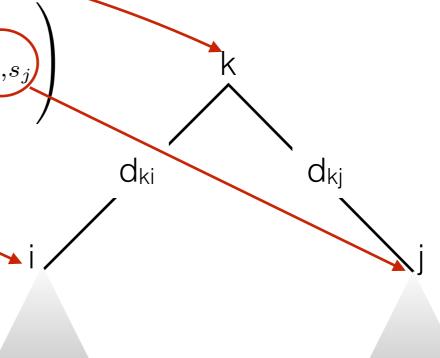
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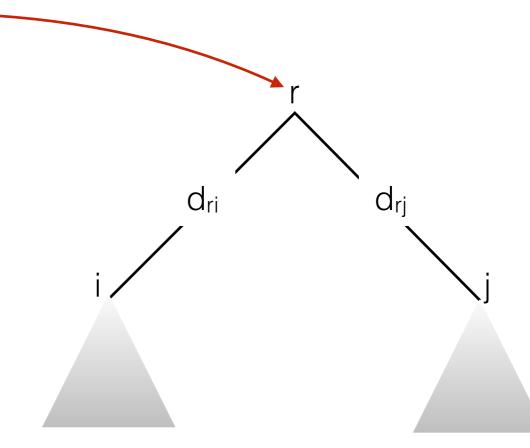
Dynamic programming: post-order traversal of the tree!



At the root, we simply sum over all possible states to get the likelihood for the entire tree:

$$\mathcal{L} = \sum_{s_r} \pi_{s_r} \mathcal{L}_{r,s_r}$$

Using these likelihoods, we can ask questions like:



What is the probability that node k had state 'A'?
What is the probability that node k didn't have state 'C'?
At node k, how likely was state 'A' compared to state 'C'?

This maximum likelihood framework is very powerful.

It allows us to consider *all* evolutionary histories, weighted by their probabilities.

Also lets us evaluate other tree parameters like branch-length.

But we there can be many assumptions baked into our *model* (and such a model is part of our ML framework)

What if our parameters are wrong?

What if our assumptions about "Markovian" mutation are wrong?

What if the *structure* of our model is wrong (correlated evolution)?

Large phylogeny problem — searching for trees

Distance-based methods:

- * Sequences -> Distance Matrix -> Tree
- * Neighbor joining, UPGMA

Maximum Likelihood:

* Sequences + Model -> Tree + parameters

Bayesian MCMC:

* Markov Chain Monte Carlo: random sampling of trees by random walk

Additivity (for distance-based methods)

- A distance matrix M is additive if a tree can be constructed such that $d_T(i,j) = path$ length from i to $j = M_{ij}$.
- Such a tree faithfully represents all the distances
- 4-point condition: A metric space is additive if, given any 4 points, we can label them so that

$$M_{xy} + M_{uv} \le M_{xu} + M_{yv} = M_{xv} + M_{yu}$$

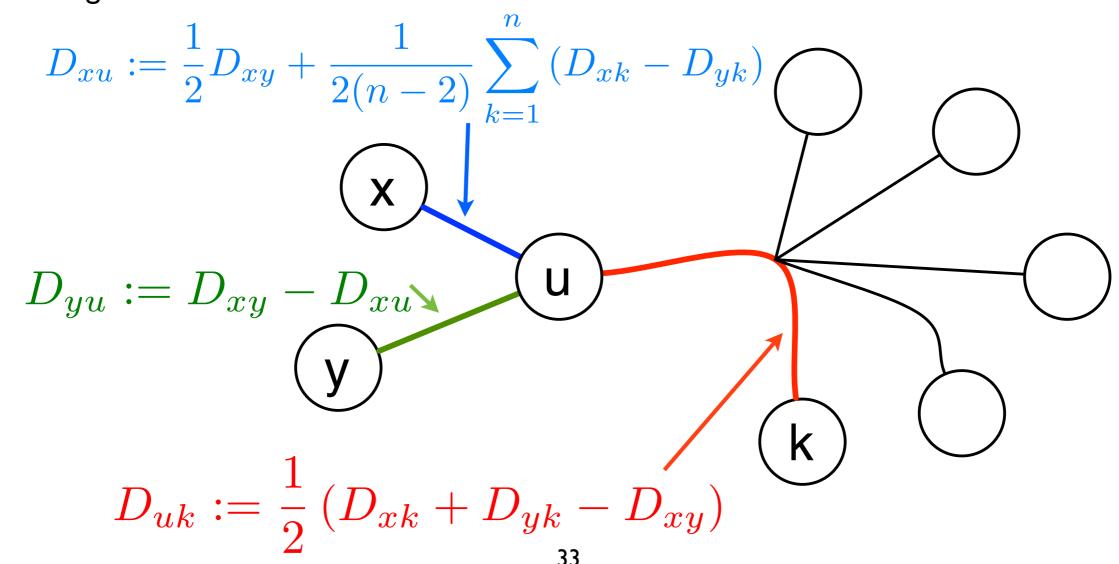
• If our metric is additive, there is exactly one tree realizing it, and it can be found by successive insertion#

Neighbor Joining

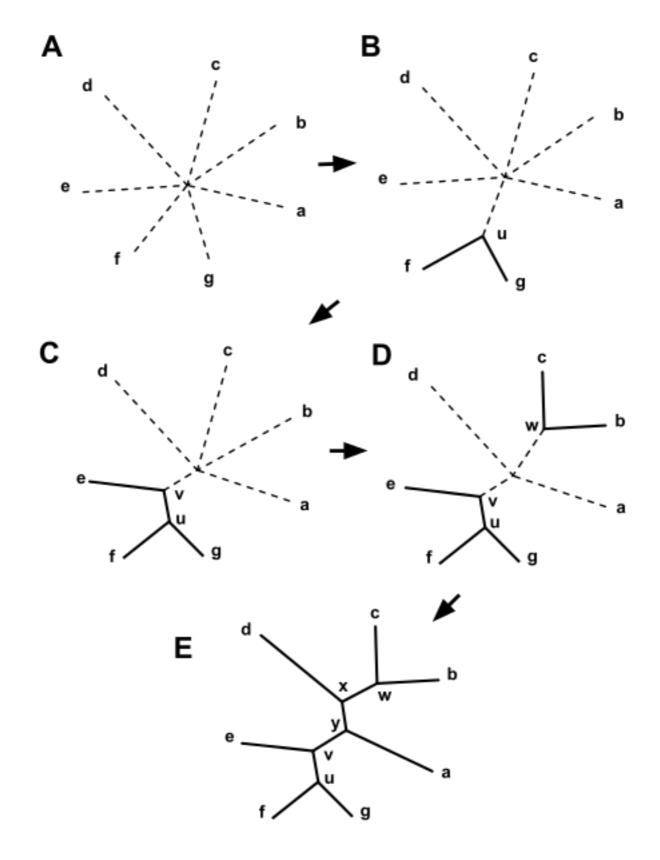
Choose x, y to merge that minimize:

$$Q(x,y) := (n-2)D_{xy} - \left(\sum_{k=1}^{n} D_{xk} + \sum_{k=1}^{n} D_{yk}\right)$$

Update lengths:



Neighbor Joining — Example



What if our distances aren't so nice?

UPGMA

- Find two most similar taxa (ie. such that M_{ij} is smallest)
- Merge into new "OTU" (operational taxonomic unit)
 - distance from k to new OTU = average distance from k to each of OTUs members
- Repeat.
- Even if there is perfect tree, it may not find it.

Maximum Parsimony

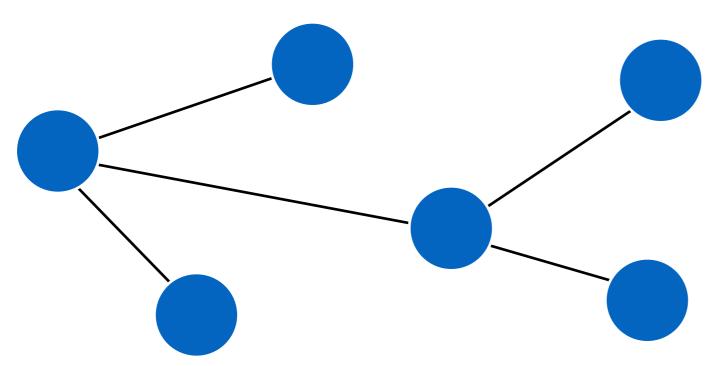
- Input: n sequences of length k
- Output: A tree T = (V, E) and a sequence s_u of length k for each node u to minimize:

$$\sum_{(u,v)\in E} \operatorname{Hamming}(s_u,s_v)$$

NP-hard (reduction from Hamming distance Steiner tree) Can score a given tree in time $O(|\Sigma|nk)$.

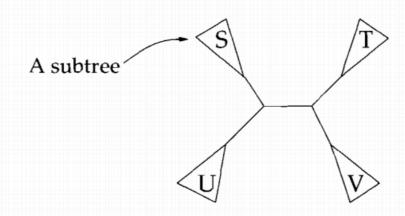
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Heuristic: Nearest Neighbor Interchange

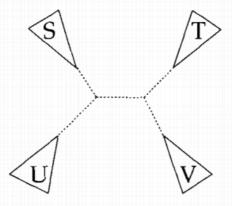


Walk from tree T to its neighbors, choosing best neighbor at each step.

Heuristic: Nearest Neighbor Interchange



is rearranged by dissolving the connections to an interior branch



and reforming them in one of the two possible alternative ways:

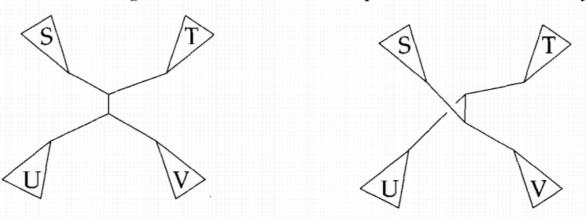


Figure 4.2: The process of nearest-neighbor interchange. An interior branch is dissolved and the four subtrees connected to it are isolated. These then can be reconnected in two other ways.

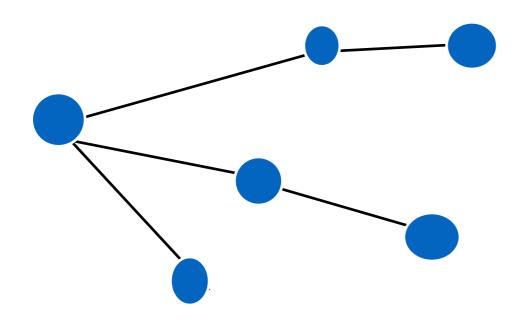
Maximum Likelihood

- Input: n sequences S₁,...,S_n of length k; choice of model
- Output: Tree T and parameters p_e for each edge to maximize:

$$Pr[S_1,...,S_n | T, p]$$

NP-hard if model is Jukes-Cantor; probably NP-hard for other models.

Bayesian MCMC



Walk from tree T to its neighbors, choosing a particular neighbor at each step with probability related to its improvement in likelihood. This walk in the space of trees is a Markov chain.

Under "mild" assumptions, and after taking many samples, trees are visited proportional to their true probabilities.

- # of times you visit a tree (after "burn in")= probability of that topology
- Outputs a distribution of trees, not a single tree.

Bootstrapping

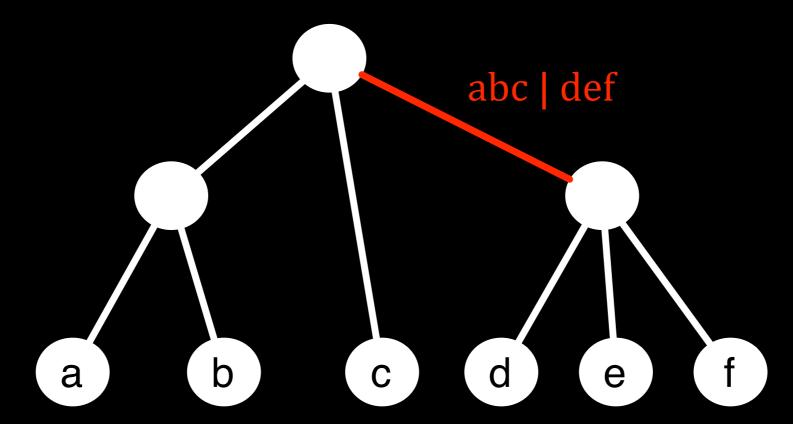
- How confident are we in a given edge?
- Bootstrapping:
 - I. Create (e.g.) 1,000 data sets of same size as input by sampling markers (MSA columns) with replacement.
 - 2. Repeat phylogenetic inference on each set.
 - 3. Support for edge is the % of trees containing this edge (bipartition).
- **Interpretation**: probability that edge would be inferred on a random data set drawn from the same distribution as the input set.

Going from an "ensemble" to a single tree

Even if we can generate such an ensemble (e.g. a collection of trees where each is proportional to its true probability).

How can we "extract" a single, meaningful, tree from this ensemble?

Splits



Every edge \Rightarrow a split, a bipartition of the taxa

- taxa within a clade leading from the edge
- taxa outside the clade leading from the edge

Example: this tree = {abc|def, ab|cdef + 'trivial' splits}

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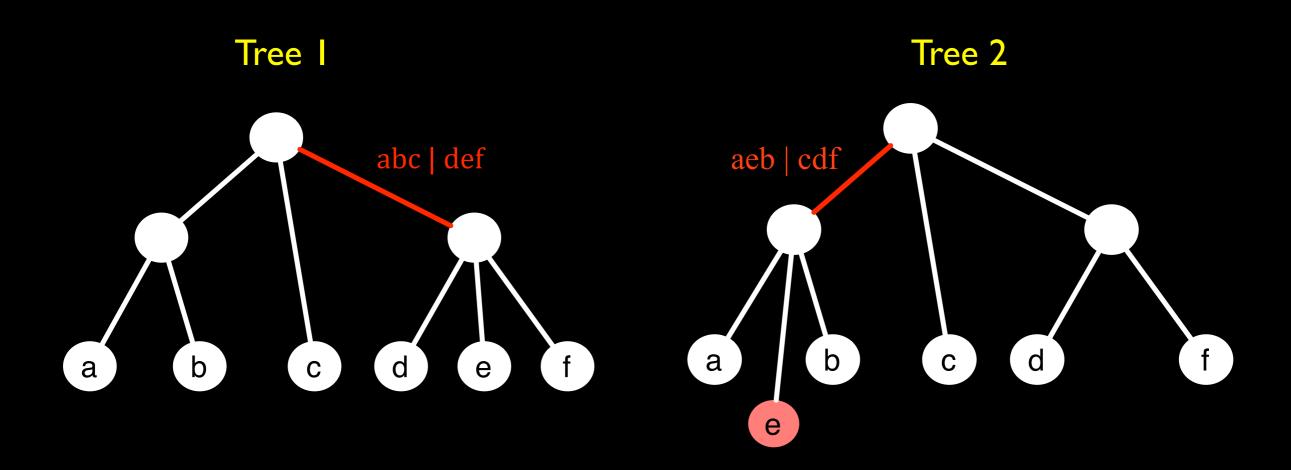
Consensus

 Multiple trees: from bootstrap, from Bayesian MCMC, trees with sufficient likelihood, same parsimony:

$$T = \{T_1,...,T_n\}$$

- Splits of T_i := C(T_i) = { b(e) : e ∈ T_i }
 b(e) is the split (bipartition) for edge e.
- Majority consensus: tree given by splits which occur in > half inferred trees.

Incompatibility



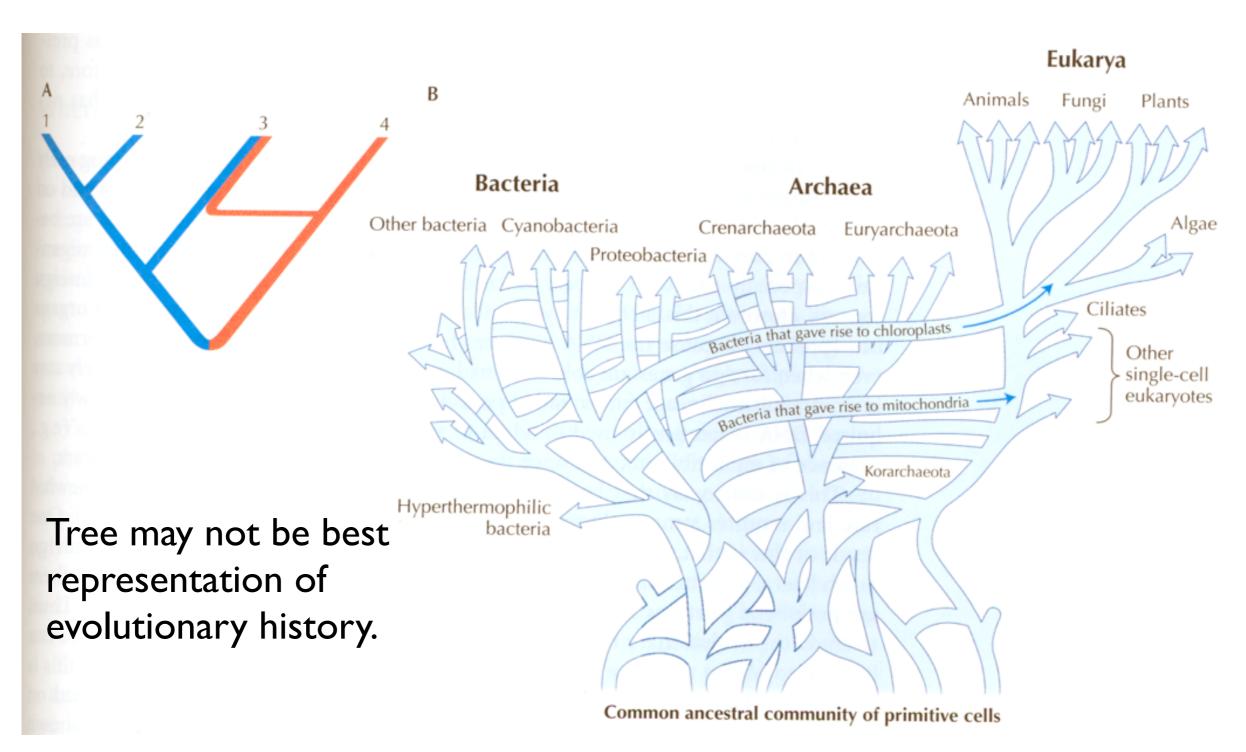
Two splits are incompatible if they cannot be in the same tree.

Majority Consensus Always Exists

• Proof:

- 1. Let $\{s_k\}$ be the splits in > half the trees.
- 2. Pigeonhole: for each s_i , s_j in $\{s_k\}$ there must be a tree containing both s_i and s_j .
- 3. If s_i and s_j are in same tree they are compatible.
- 4. Any set of compatible splits forms a tree.
- \Rightarrow The $\{s_i\}$ are pairwise compatible and form a tree.

Horizontal Gene Transfer



DNA uptake; retroviruses