CSE 549: Efficiently Dealing with k-mers and De Bruijn Graphs



# Scalability at the forefront

I've spoken a lot in this class about the need for scalable solutions, but how big of a problem is it?

Take (one of) the simplest problems you might imagine: Given: A collection of sequencing reads S and a paramater k

Find: The multiplicity of every length-k substring (k-mer) that appears in S

This is the *k-mer counting* problem

### k-mer counting

A large number of recent papers tackle this (or a closely related) problem:

Tallymer, Jellyfish, DSK, KMC, BFCounter, scTurtle, KAnalyze, khmer, ... and many more

### How might we count k-mers

A naive approach:



# What's wrong with this approach?

Speed & Memory usage

Routinely encounter datasets with 10 - 100 x 10<sup>9</sup> nucleotides

Just hashing the k-mers and resolving collisions takes time

On the order of 1-10 x 10<sup>9</sup> or more distinct k-mers

If we used a 4-byte unsigned int to store the count, we'd be using 40GB just for counts

But, hashes have overhead (load factor < 1), and often need to store the *key* as well as the *value* 

Easily get to > 100GB of RAM

### Smart, parallel hashing actually pretty good

If we put some thought and engineering effort into the hashing approach, it can actually do pretty well. This is the insight behind the Jellyfish program.

Massively parallel, *lock-free*, k-mer counting

- most parallel accesses won't cause a collision

Efficient storage of hash table values

- bit-packed data structure
- small counter with multiple entries for high-count k-mers

Efficient storage of keys

- f:  $U_k \rightarrow U_k$ , and let hash(k) = f(k) mod M

Can reconstruct k from pos in hash table (quotient) and remainder.

Smart, parallel hashing actually pretty good Efficient storage of keys

- f:  $U_k \rightarrow U_k$ , and let hash(k) = f(k) mod M

— recall: we can represent f(k) as f(k) = qM + r

- Can reconstruct k from pos in hash table (quotient, q) and remainder, r. The quotient is simply encoded as the position.
- Extra work must be done since collisions can occur
- For a general coverage of this idea, see the Quotient Filter data structure by Bender et al. (2011)

### Squeakr: An Exact and Approximate *k*-mer Counting System

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# Memory usage of Jellyfish



# Runtime of Jellyfish



# System utilization of Jellyfish





# Even bigger data

For very large datasets, even this approach may use too much memory. How can we do better?

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For very large datasets, even this approach may use too much memory. How can we do better?

Solve a different (but closely-related) problem

What if we just want to know "if" a k-mer is present?

# **Bloom Filters**

Originally designed to answer *probabilistic* membership queries:

Is element e in my set S?

If yes, **always** say yes

If no, say no with large probability

False positives can happen; false negatives cannot.

# **Bloom Filters**

For a set of size N, store an array of M bits Use k different hash functions,  $\{h_0, ..., h_{k-1}\}$ To insert e, set A[ $h_i(e)$ ] = 1 for 0 < i < k To query for e, check if A[ $h_i(e)$ ] = 1 for 0 < i < k



Image by David Eppstein - self-made, originally for a talk at WADS 2007

# **Bloom Filters**

If hash functions are good and sufficiently independent, then the probability of false positives is low and controllable.

How low?



Image by David Eppstein - self-made, originally for a talk at WADS 2007

Let q be the fraction of the m-bits which remain as 0 after n insertions.

The probability that a randomly chosen bit is 1 is 1-q.

But we need a 1 in the position returned by k different hash functions; the probability of this is  $(1-q)^k$ 

We can derive a formula for the expected value of q, for a filter of m bits, after n insertions with k different hash functions:

$$E[q] = (1 - 1/m)^{kn}$$

Mitzenmacher & Unfal used the Azuma-Hoeffding inequaltiy to prove (without assuming the probability of setting each bit is independent) that

$$\Pr(|q - E[q]| \ge \frac{\lambda}{m}) \le 2\exp(-2\frac{\lambda^2}{m})$$

That is, the random realizations of q are highly concentrated around E[q], which yields a false positive prob of:

$$\sum_{t} \Pr(q=t)(1-t)^{k} \approx (1-E[q])^{k} = \left(1 - \left[1 - \frac{1}{m}\right]^{kn}\right)^{k} \approx (1 - e^{-\frac{kn}{m}})^{k}$$

\*analysis of Mitzenmacher and Upfal

$$\sum_{t} \Pr(q=t)(1-t)^{k} \approx (1-E[q])^{k} = \left(1 - \left[1 - \frac{1}{m}\right]^{kn}\right)^{k} \approx (1 - e^{-\frac{kn}{m}})^{k}$$

This lets us choose optimal values to achieve a target false positive rate. For example, assume m & n are given. Then we can derive the optimal k

$$k = (m/n) \ln 2 \implies 2^{-k} \approx 0.6185 \text{ m/n}$$

We can then compute the false positive prob

$$p = (1 - e^{-(\frac{m}{n}\ln 2)\frac{n}{m}})^{(\frac{m}{n}\ln 2)} \implies$$
$$\ln p = -\frac{m}{n}(\ln 2)^2 \implies$$
$$m = -\frac{n\ln p}{(\ln 2)^2}$$

$$\sum_{t} \Pr(q=t)(1-t)^{k} \approx (1-E[q])^{k} = \left(1 - \left[1 - \frac{1}{m}\right]^{kn}\right)^{k} \approx (1 - e^{-\frac{kn}{m}})^{k}$$

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We can then compute the false positive prob

$$p = (1 - e^{-(\frac{m}{n} \ln 2)\frac{n}{m}})^{(\frac{m}{n} \ln 2)} \implies \qquad \text{given an expected} \\ \ln p = -\frac{m}{n}(\ln 2)^2 \implies \qquad \text{and a desired} \\ \text{false positive rate} \\ m = (\ln 2)^2 \qquad \text{we can compute} \\ \text{the optimal size and} \\ \# \text{ of has functions} \end{cases}$$

### Detour: Bloom Filters & De Bruijn Graphs

How could this data structure be useful for representing a De Bruijn graph?

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Say we have a bloom filter B, for all of the k-mers in our data set, and say I give you one k-mer that is truly present.

We now have a "navigational" representation of the De Bruijn graph (can return the set of neighbors of a node, but not select/iterate over nodes); why?

### Detour: Bloom Filters & De Bruijn Graphs

How could this data structure be useful for representing a De Bruijn graph?



A given (k-1)-mer can only have  $2^*|\Sigma|$  neighbors; | $\Sigma|$  incoming and | $\Sigma|$  outgoing neighbors — for genomes | $\Sigma| = 4$ 

To navigate in the De Bruijn graph, we can simply query all possible successors, and see which are actually present.

### Bloom Filters & De Bruijn Graphs

But, a Bloom filter still has false-positives, right?

May return some neighbors that are not actually present.

Pell et al., PNAS 2012, use a lossy Bloom filter directly

Chikhi & Rizk, WABI 2012, present a *lossless* datastructure based on Bloom filters

Salikhov et al., WABI 2013 extend this work and introduce the concept of "cascading" Bloom filters

# Idea of Chkhi and Rizk

Assume we want to represent specific set T0 of k-mers with a Bloom filter B1

*Key observation:* in assembly, not all k-mers can be queried, only those having k-1 overlap with k-mers known to be in the graph.

The set T1 of "critical false positives" (false neighbors of true k-mers) is *much* smaller than the set of all false positives and can be stored explicitly

Storing B1 and T1 is much more space efficient that other exact methods for storing T0. Membership of w in T0 is tested by first querying B1, and if  $w \in B1$ , check that it is *not* in T1.





#### • Represent $T_0$ by Bloom filter $B_1$



Represent T<sub>0</sub> by Bloom filter B<sub>1</sub>

Compute T<sub>1</sub> ('critical false positives') and represent it e.g.
 by a hash table



Represent T<sub>0</sub> by Bloom filter B<sub>1</sub>

- Compute T<sub>1</sub> ('critical false positives') and represent it e.g.
  by a hash table
- Result (example): 13.2 bits/node for k=27 (of which 11.1 bits for B<sub>1</sub> and 2.1 bits for T<sub>1</sub>)

### Improving on Chikhi and Rizk's method

- Main idea: iteratively apply the same construction to  $T_1$  i.e. encode  $T_1$  by a Bloom filter  $B_2$  and set of 'false-false positives'  $T_2$ , then apply this to  $T_2$  etc.
- Cascading Bloom filters







• further encode  $T_1$  via a Bloom filter  $B_2$  and set  $T_2$ , where  $T_2 \subseteq T_0$  is the set of k-mers stored in  $B_2$  by mistake ('false<sup>2</sup> positives')





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- ▶ iterate the construction on T<sub>2</sub>
- we obtain a sequence of sets T<sub>0</sub>, T<sub>1</sub>, T<sub>2</sub>, T<sub>3</sub>, ... encode by Bloom filters B<sub>1</sub>, B<sub>2</sub>, B<sub>3</sub>, B<sub>4</sub>, ... respectively

► 
$$T_0 \supseteq T_2 \supseteq T_4 \supseteq \dots, T_1 \supseteq T_3 \supseteq T_5 \supseteq$$



<u>Lemma [correctness]</u>: For a k-mer w, consider the smallest i such that  $w \notin B_{i+1}$ . Then  $w \in T_0$  if i is odd and  $w \notin T_0$  if i is even.

- if  $w \notin B_1$  then  $w \notin T_0$
- if  $w \in B_1$ , but  $w \notin B_2$  then  $w \in T_0$
- if  $w \in B_1$ ,  $w \in B_2$ , but  $w \notin B_3$  then  $w \notin T_0$
- etc.

### Assuming infinite number of filters

Let  $N=|T_0|$  and  $r=m_i/n_i$  is the same for every  $B_i$ . Then the total size is

 $\frac{rN + 6rNc^{r} + rNc^{r} + 6rNc^{2r} + rNc^{2r} + ... = N(1+6c^{r})\frac{r}{1-c^{r}}}{|B_{1}| |B_{2}| |B_{3}| |B_{4}| |B_{4}| |B_{5}|}$ 

The minimum is achieved for *r*=5.464, which yields the memory consumption of 8.45 bits/node



### Infinity difficult to deal with ;)

- In practice we will store only a small finite number of filters  $B_1, B_2, \ldots, B_t$  together with the set  $T_t$  stored explicitly
- t=1 → Chkhi&Rizk's method

 The estimation should be adjusted, optimal value of r has to be updated, example for t=4

k	optimal $r$	bits per $k$ -mer
16	5.776737	8.555654
32	6.048557	8.664086
64	6.398529	8.824496
128	6.819496	9.045435

**Table**: Estimations for t=4. Optimal *r* and corresponding memory consumption



### Compared to Chikhi&Rizk's method

k	"Optimal" (infinite)	Cascading Bloom Filter	Data structure
	Cascading Bloom Filter	with $t = 4$	of Chikhi & Rizk
16	8.45	8.555654	12.0785
32	8.45	8.664086	13.5185
64	8.45	8.824496	14.9585
128	8.45	9.045435	16.3985

**Table**: Space (bits/node) compared to Chikhi&Rizk for *t*=4 and different values of *k*.



### We can cut down a bit more ...

- Rather than using the same r for all filters  $B_1, B_2, ..., we$  can use different properly chosen coefficients  $r_1, r_2, ...$
- This allows saving another 0.2 0.4 bits/k-mer



### Experiments I: E.Coli, varying k

- 10M E.Coli reads of 100bp
- 3 versions compared: 1 Bloom (=Chikhi&Rizk), 2 Bloom (t=2) and 4 Bloom (t=4)



### Experiments II: Human dataset

564M Human reads of 100bp (~17X coverage)

Method	1 Bloom	2 Bloom	4 Bloom
Construction time (s)	40160.7	43362.8	44300.7
Traversal time (s)	46596.5	35909.3	34177.2
r (bits)	11.10	8.10	6.56
	$B_1 = 3250.95$	$B_1 = 2372.51$	$B_1 = 1921.20$
Bloom filters size (MB)		$B_2 = 292.65$	$B_2 = 496.92$
Diooni inters size (WID)			$B_3 = 83.39$
			$B_4 = 21.57$
False positive table size (MB)	$T_1 = 545.94$	$T_2 = 370.96$	$T_4=24.07$
Total size (MB)	3796.89	2524.12	2547.15
Size (bits/k-mer)	12.96	10.37	8.70

### Experiments I (cont)



# Efficiently enumerating cFP

Algorithm 1 Constant-memory enumeration of critical false positives

- Input: The set S of all nodes in the graph, the Bloom filter constructed from S, the maximum number M of elements in each partition (determines memory usage)
- 2: Output: The set cFP
- 3: Store on disk the set  $\mathcal{P}$  of extensions of  $\mathcal{S}$  for which the Bloom filter answers *yes*
- 4: Free the Bloom filter from memory
- 5:  $D_0 \leftarrow \mathcal{P}$
- 6: *i* ← 0
- 7: while end of  $\mathcal{S}$  is not reached **do**
- 8:  $P_i \leftarrow \emptyset$
- 9: while  $|P_i| < M$  do
- 10:  $P_i \leftarrow P_i \cup \{\text{next } k \text{-mer in } S\}$
- 11: **for** each *k*-mer m in  $D_i$  **do**
- 12: **if**  $m \notin P_i$  **then**
- 13:  $D_{i+1} \leftarrow D_{i+1} \cup \{m\}$
- 14: Delete  $D_i$ ,  $P_i$
- 15:  $i \leftarrow i+1$
- 16: cFP  $\leftarrow D_i$

# Bloom filters & De Bruijn Graphs

So, we can use Bloom filters to help efficiently represent De Bruijn Graphs.

Other variants (e.g. counting Bloom filters (Melsted & Pritchard, BMC Bioinformatics, 2011)) allow us to count approximate occurrences of each k-mer, allowing us to sidestep huge storage requirements for k-mers occurring exactly once.

Such an idea is implemented in BFCounter, and brings us back, full-circle, to the problem of counting k-mers!

Some recent methods apply Bloom filters or related ideas to the problem of k-mer counting. One such method is khmer, which uses the count-min sketch data structure.

Instead of a an array of m-bits, store a 2D, array, CM, of size d x w — d is called the depth of the array, and there are d *independent* hash functions, w is called with width of the array. This is an O(wd) data structure.



Like Bloom filters, 2 mains operations:

Update (k, v) — for each entry CM[i,  $h_i(k)$ ], where 0 < i < d, increment the value by v.

Query (k) — compute v = min CM[i,  $h_i(k)$ ]

Both are O(d) operations



Similar error analysis to Bloom filters (won't prove bounds)

Let  $\hat{a}_i$  be the result returned by Query(i). We have that:

(always)  $a_i \leq \hat{a_i}$ (with probability at least  $\frac{1}{s}$ )  $\hat{a}_i \leq a_i + \epsilon ||\mathbf{a}||_1$ where,  $w = \left\lceil \frac{e}{\epsilon} \right\rceil, d = \left\lceil \ln(\frac{1}{\delta}) \right\rceil, \text{ and } ||\mathbf{a}||_1 = \sum_{i=1}^{r} |a_i|$ 

Similar error analysis to Bloom filters (won't prove bounds)

Let  $\hat{a}_i$  be the result returned by Query(i). We have that:



### The Count-Min Sketch for k-mer counting

This approach is used in the k-mer counting software khmer

No exact data structure is maintained, just a CMS

This allows for answering approximate count queries efficiently.

Authors compared to a large number of other k-mer counters under several different metrics.







# Querying for random k-mers



### Miscount & FP rate; changing $\epsilon$ and $\delta$



### Miscount & FP-rate



### Other uses of this approach

# Khmer has been used successfully for other tasks e.g. digital normalization:

### diginorm algo:

for read in dataset:

if estimated\_coverage(read) < C:

accept(read)

else:

discard(read)

# median k-mer abundance of k-mers in the read

memory	FP rate	retained reads	retained reads %	true k-mers missing	total k-mers
before diginorm	-	5,000,000	100.0%	170	41.6 m
2400 MB	0.0%	1,656,518	33.0%	172	28.1 m
240 MB	2.8%	1,655,988	33.0%	172	28.1 m
120 MB	18.0%	1,652,273	33.0%	172	28.1 m
60 MB	59.1%	1,633,182	32.0%	172	27.9 m
40 MB	83.2%	1,602,437	32.0%	172	27.6 m
20 MB	98.8%	1,460,936	29.0%	172	25.7 m
10 MB	100.0%	1,076,958	21.0%	185	20.9 m

The results of digitally normalizing a 5 m read *E. coli* data set (1.4 GB) to C = 20 with k = 20 under several memory usage/false positive rates. The false positive rate (column 1) is empirically determined. We measured reads remaining, number of "true" k-mers missing from the data at each step, and the number of total k-mers remaining. Note: at high false positive rates, reads are erroneously removed due to inflation of k-mer counts. doi:10.1371/journal.pone.0101271.t004

# Work along these lines at SBU

#### A General-Purpose Counting Filter: Making Every Bit Count

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Bioinformatics 33/bioinformatics/xxxxxx in Date: Day Month Year Manuscript Category

OXFORD

Genome analysis

### Squeakr: An Exact and Approximate *k*-mer Counting System

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OXFORD

### deBGR: an efficient and near-exact representation of the weighted de Bruijn graph

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Mantis: A Fast, Small, and Exact Large-Scale Sequence-Search Index

Prashant Pandey<sup>1</sup>, Fatemeh Almodaresi<sup>1</sup>, Michael A. Bender<sup>1</sup>, Michael Ferdman<sup>1</sup>, Rob Johnson<sup>2,1</sup>, and Rob Patro<sup>1</sup>

# The Counting Quotient Filter

Compact, lossless representation of multiset h(S)

h : U  $\rightarrow$  {0,...,2<sup>p</sup>-1} is a hash function, S is multiset, U is the universe from which S is drawn

 $x \in S$ , h(x) is a p-bit number.

Q is an array of 2<sup>q</sup> r-bit slots

The quotient filter divides h(x) into q(h(x)), r(h(x)); the first q and remaining r bits of h(x) where p=q+r

Put r(h(x)) into Q[q(h(x))]

# The Counting Quotient Filter

In reality, a bit more complicated because collisions can occur. What if Q[q(h(x))] is occupied by some other element (as the result of an earlier collision)?



Figure 1: A simple rank-and-select-based quotient filter. The colors are used to group slots that belong to the same run, along with the runends bit that marks the end of that run and the occupieds bit that indicates the home slot for remainders in that run.

Move along until you find the next free slot. Metadata bits allow us to track "runs" and skip elements other than the key of interest efficiently.

# The Counting Quotient Filter

How to count?

Rather than having a separate array for counting (a *la* the counting Bloom filter), use the slots of Q directly to encode either r(h(x)), or counts!

The CQF uses a somewhat complex encoding scheme (base 2<sup>r</sup>-2), but this allows arbitrary variable length counters.

This is a **huge** win for highly-skewed datasets with non-uniform counts (like most of those we encoutner).



Figure 4: Number of bits per element for the RSQF, QF, BF, and CF. The RSQF requires less space than the CF and less space than the BF for any false-positive rate less than 1/64. (Higher is better)

Data Structure	CQF	CBF
Zipfian random inserts per sec	13.43	0.27
Zipfian successful lookups per sec	19.77	2.15
Uniform random lookups per sec	43.68	1.93
Bits per element	11.71	337.584

(b) In-memory Zipfian performance (in millions of operations per second).



Figure 5: Space comparison of CQF, SBF, and CBF as a function of the number of distinct items. All data structures are built to support up to  $n = 1.6 \times 10^7$  insertions with a false-positive rate of  $\delta = 2^{-9}$ .



Figure 8: In-memory performance of the CQF and CBF on data with a Zipfian distribution. We don't include the CF in these benchmarks because the CF fails on a Zipfian input distribution. The load factor does not go to 95% in these experiments because load factor is defined in terms of the number of distinct items inserted in the data structure, which grows very slowly in skewed data sets. (Higher is better.)



(a) CQF in-memory insert performance on appli- (b) CQF multi-threaded in-memory insert perfor- (c) Percent of slots in use in a counting quotient filter vs. the number of distinct items inserted from a Zipfian distribution with C=1.5 and a universe of 201M. We performed a total of 201M inserts.

Figure 9: In-memory performance of the counting quotient filter with real-world data sets and with multiple threads, and percent slot usage with skewed distribution.

### Squeakr, applying the CQF to k-mer counting Counting Memory

Table 1. datasets used in the experiments

Dataset	File size	#Files	# k-mer instances	#Distinct k-mers
F.vesca	3.3	11	4 134 078 256	632 436 468
G.gallus	25.0	15	25 337 974 831	2 727 529 829
M.balbisiana	46.0	2	41 063 145 194	965 691 662
H.sapiens 1	67.0	6	62 837 392 588	6 353 512 803
H.sapiens 2	99.0	48	98 892 620 173	6 634 382 141

Note: The file size is in GB. All the datasets are compressed with gzip compression.

Table 2. Gigabytes of RAM used by KMC2, Squeakr, Squeakr-exact,
and Jellyfish2 for various datasets for in-memory experiments for
<i>k</i> =28

dataset	KMC2	Squeakr	Squeakr-exact	Jellyfish2
F.vesca	8.3	4.8	9.3	8.3
G.gallus	32.8	13.0	28.8	31.7
M.balbisiana	48.3	11.1	14.2	16.3
H.sapiens 1	71.4	22.1	51.5	61.8
H.sapiens 2	107.4	30.8	60.1	61.8

### Squeakr, applying the CQF to k-mer counting Counting performance

System	F.vesca		G.gallus		M.balbisiana		H.sapiens 1		H.sapiens 2	
	8	16	8	16	8	16	8	16	8	16
KMC2	91.68	67.76	412.19	266.546	721.43	607.78	1420.45	848.79	1839.75	1247.71
Squeakr	116.56	64.44	739.49	412.82	1159.65	662.53	1931.97	1052.73	3275.20	1661.77
Squeakr-exact Jellyfish2	146.56 257.13	80.58 172.55	966.27 1491.25	501.77 851.05	1417.48 1444.16	763.88 886.12	2928.06 4173.3	1667.98 2272.27	5016.46 6281.94	2529.46 3862.82

Table 3. k-mer counting performance of KMC2, Squeakr, Squeakr-exact, and Jellyfish2 on different datasets for k=28

Table 4. k-mer counting performance of KMC2, Squeakr, and Jellyfish2 on different datasets for k=55

System	F.vesca		G.gallus		M.balbisiana		H.sapiens 1		H.sapiens 2	
	8	16	8	16	8	16	8	16	8	16
KMC2	233.74	123.87	979.20	1117.35	1341.01	1376.51	3525.41	2627.82	4409.82	3694.85
Squeakr	138.32	75.48	790.83	396.36	1188.15	847.83	2135.71	1367.56	3320.67	2162.97
Jellyfish2	422.220	294.93	1566.79	899.74	2271.33	1189.01	3716.76	2264.70	6214.81	3961.53

### Squeakr, applying the CQF to k-mer counting Query performance

**Table 5.** Random query performance of KMC2, Squeakr, Squeakrexact, and Jellyfish2 on two different datasets for *k*=28

System	G.gallus		M.balbisiana			
	Existing	Non-existing	Existing	Non-existing		
KMC2	1495.82	470.14	866.93	443.74		
Squeakr	303.68	52.45	269.24	40.73		
Squeakr-exact	389.58	58.46	280.54	42.67		
Jellyfish2	884.17	978.57	890.57	985.30		

System	Dataset	Max path len	Running times		
			Counting	Query	Total
KMC2	G.gallus	122	266	23 097	23 363
Squeakr	G.gallus	92	412	3415	3827
KMC2	M.balbisiana	123	607	6817	7424
Squeakr	M.balbisiana	123	662	1471	2133

Note: The counting time is calculated using 16 threads. The query time is calculated using a single thread. Time is in seconds. We excluded Jellyfish2 from this benchmark because Jellyfish2 performs slowly compared to KMC2 and Squeakr for both counting and query (random query and existing k-mer query).

### Take-home message

The sheer scale of the data we have to deal with makes even the most simple tasks (e.g. counting k-mers or storing and traversing a De Bruin graph) rife with opportunities for the development and application of interesting and novel data structures and algorithms!